

SANMOTION

CLOSED LOOP STEPPING SYSTEMS

Model No.PB



Ver.3

SANYO DENKI

English

Hybrid system combining the ease-of-use of stepping motors with the reliability of servomotors.

SANMOTION Model No. PB

CLOSED LOOP STEPPING SYSTEMS

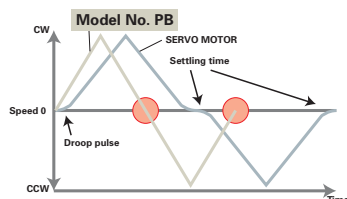
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Increased System Speed and Smaller System Size

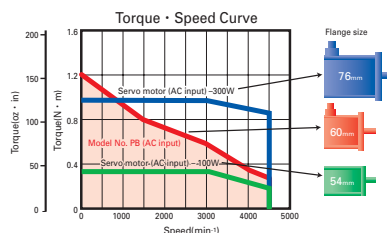
High Speed Positioning

High torque performance in the low speed range delivers shorter positioning time for short stroke/high hit rate applications.



Smaller System Size

Smaller system size is achievable for low speed applications due to the availability of higher torque performance in the low speed range as compared to conventional servomotors.

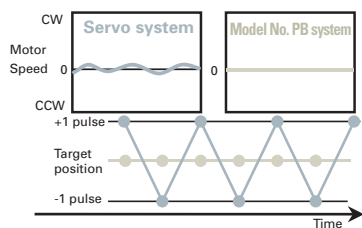


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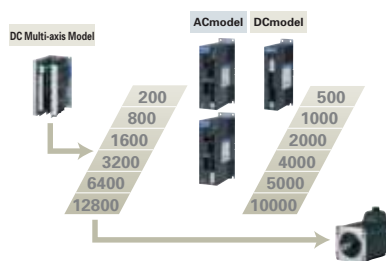
Stable Stand-Still

Complete stand-still motion is possible due to the availability of holding torque, a typical characteristic of stepping motors.



High Resolution

The position resolution can be subdivided for higher positioning precision.



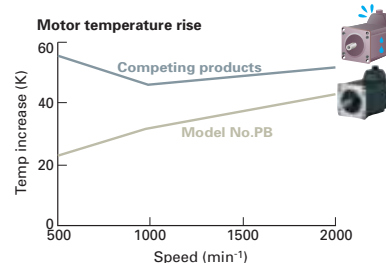
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Energy-Saving

Improved Efficiency from Current Control

Higher efficiency from low heat generation is achieved by controlling the current flow to motor according to motor load.



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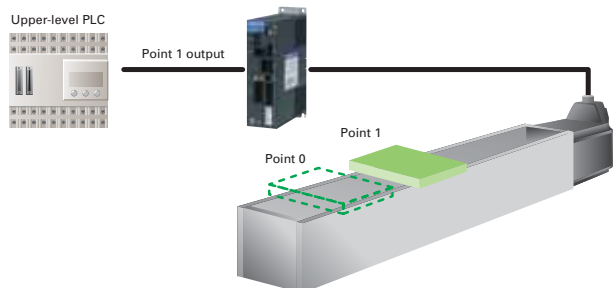
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Simplified Control

General Purpose I/O Input

A	Type	D	Type	D	Type
C	R	C	M	C	R
					Multi Axis

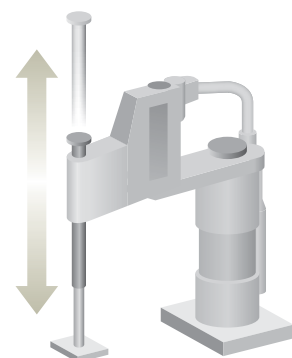
System can be easily controlled by using the general purpose I/O to designate preset point or program numbers (up to 256 points).



Support For Various Operations

A	Type	D	Type	D	Type
C	R	C	M	C	R
					Multi Axis

Comprehensive built-in amplifier functionality includes thrust control, point designation, programming, homing, holding brake control and sensor limit input.



AC Power Input

AC	Type	R	General Purpose I/O Input Type (RS-485 + PIO)
	Type		
AC	Type	P	Pulse-Train Input Type
	Type		

DC Power Input

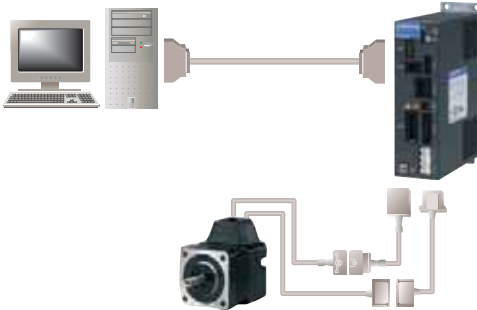
DC	Type	M	Multiple Input Type (General Purpose I/O Input + Pulse-Train Input)
	Type		
DC	Type	R	General Purpose I/O Input Type (RS-485 + PIO)
	Type		

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Reduced System Design Cost and Time

Wide Availability of Optional Cables and Connectors

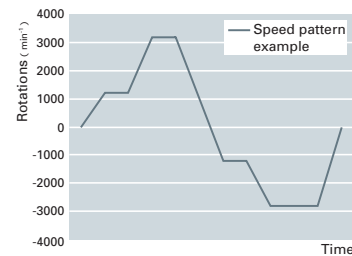
Cables and connectors for controller/amplifier and amplifier/motor connection are available for hassle-free setup.



Built-in Pulse Generation Function

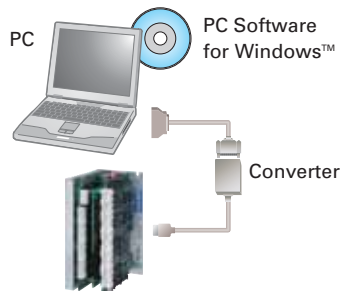
AC	Type	R	General Purpose I/O Input Type (RS-485 + PIO)
	Type		
DC	Type	M	Multiple Input Type (General Purpose I/O Input + Pulse-Train Input)
	Type		
DC	Type	R	General Purpose I/O Input Type (RS-485 + PIO)
	Type		

A built-in pulse generation function is included in the Model No. PB Types R and M. The amplifier receives speed, acceleration/deceleration and distance as numeric data from the upper-level device, and automatically generates an optimal speed pattern according to the commands internally. Since no separate pulse generator is required, this contributes to lower system cost.



PC Interface

Parameter setting, data editing and monitoring of position and speed can be done on a PC using the bundled setup software.

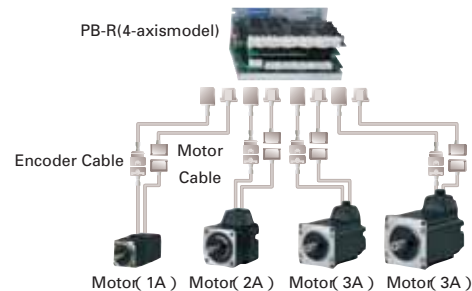


Multi-Axis Type (DC Power Input)

DC	Type	R	General Purpose I/O Input Type (RS-485 + PIO)
	Type		

Multi-axis systems can be reduced in size and weight using the PB-R 4-axis type.

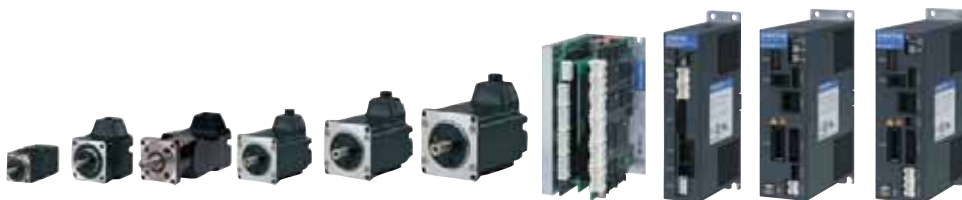
1,2,3A can be selected using software switches.



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Complies with International Safety Standards

CE cUL[®] US Compliant



Features and Functions

Type R

Type P

Type M

Type R Multi-Axis

Type R Multi-Axis

General Specifications

Motor Dimensional Drawings

Options

Extensive Closed-Loop Stepping System Lineup

SANMOTION Model No. PB

CLOSED LOOP STEPPING SYSTEMS

How do you want to control the equipment?

The Model No. PB Series offers 3 types of control methods.

Point Command
Control using PLC I/O

Network Control using Serial
Communication (RS-485)

Control using a Pulse
Generator

Power Source

AC Power Source

DC Power Source

Power Source

DC Power
Source

AC Power
Source

AC Power Source

Type R



Startup via I/O

Startup preset points or programs in the amplifier memory using the I/O.

Startup via Serial Communication

Control by transmitting speed, acceleration/deceleration and distance data via serial communication.

DC Power Source

Type R Multi-Axis



Startup via I/O

Startup preset points or programs in the amplifier memory using the I/O.

Startup via Serial Communication

Control by transmitting speed, acceleration/deceleration and distance data via serial communication.

DC Power Source

Type M



Startup via I/O

Startup preset points or programs in the amplifier memory using the I/O.

Startup via Serial Communication

Control by transmitting speed, acceleration/deceleration and distance data via serial communication.

Motion is generated by responding to pulse input commands from an upper-level controller.

AC Power Source

Type P



Motion is generated by responding to pulse input commands from an upper-level controller.



Standard Model

The standard model includes an amplifier and a motor

Motor Flange Size






AC	42 (1.65in)	60 (2.36in)	86 (3.39in)	▶ P23
DC	28 (1.10in)	42 (1.65in)	60 (2.36in)	



Low-backlash Gear Model

This model includes a low-backlash gear that engages the final stage with a tapered gear.

Motor Flange Size

AC	42 (1.65in)	60 (2.36in)	▶ P25		
DC	42 (1.65in)	60 (2.36in)			
REDUCTION GEAR RATIO	 1/3.6	 1/7.2	 1/10	 1/20	 1/30



Spur Gear Model

This model utilizes a spur gear design for gear reduction.

Motor Flange Size

DC

28

(1.10in)

▶

P29

REDUCTION GEAR RATIO

1/3.6

1/7.2

1/10

1/20

1/30

1/50



Harmonic Gear Model

The harmonic gear provides high torque and eliminates backlash.

Motor Flange Size

AC	42 (1.65in)	60 (2.36in)	▶ P31
DC	28 (1.10in)	42 (1.65in)	60 (2.36in)
REDUCTION GEAR RATIO	1/30	1/50	1/100



Electromagnetic Brake Model

This model uses a non-excitation electromagnetic brake, capable of maintaining position and supporting a load in vertical operation, even when power is off

Motor Flange Size

AC	42 (1.65in)	60 (2.36in)	▶ P33
DC	28 (1.10in)	42 (1.65in)	60 (2.36in)

Features and Functions

Type R

Type P

Type M

Type R Multi-Axis

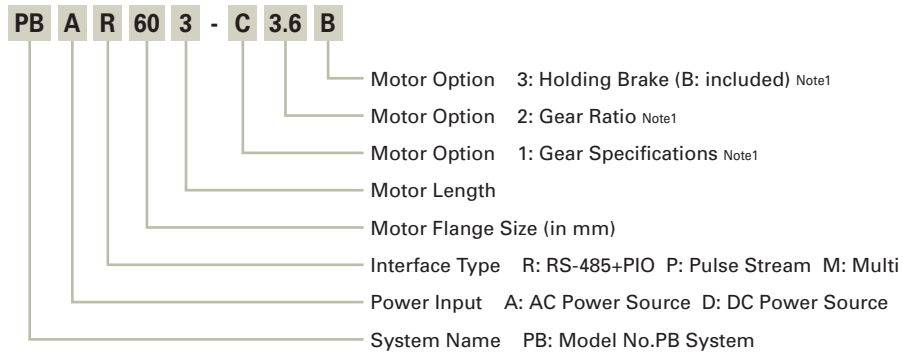
General Specifications

Motor Dimensional Drawings

Options

Model Nomenclature

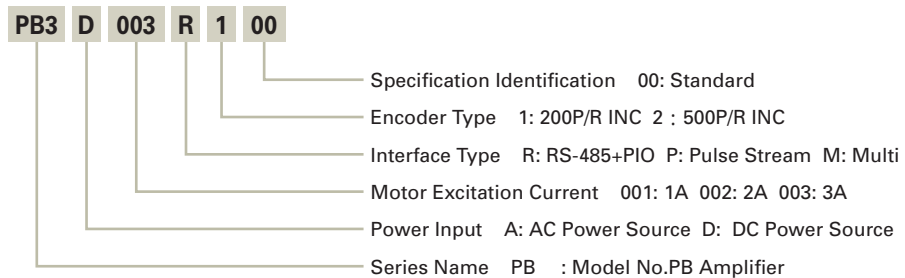
System Model Nomenclature



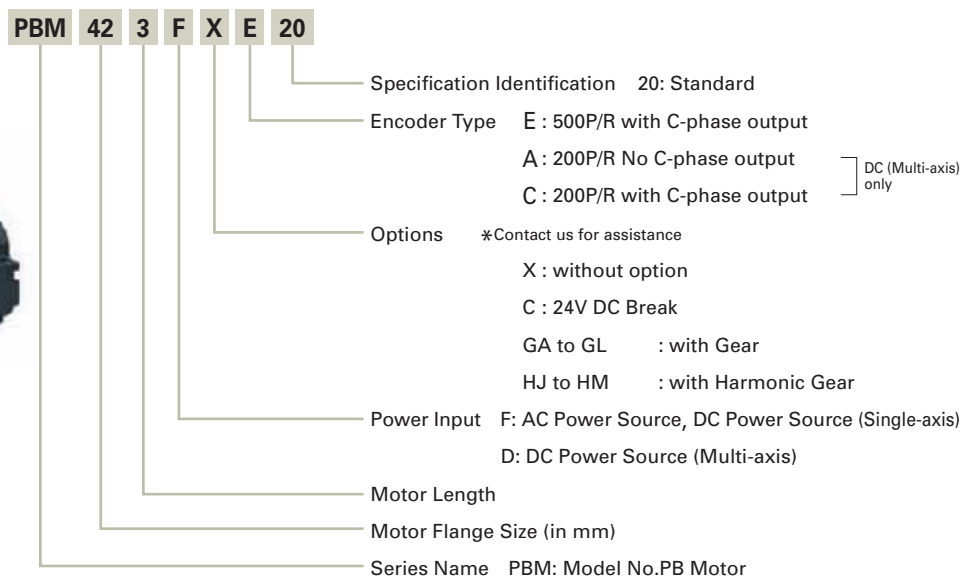
Note 1: No symbol indicates no options.

Note 2: Power(39.37inch) and I/O (39.37inch) cables are included in the set models.

Amplifier Model Nomenclature



Motor Model Nomenclature



*Please enquire separately for the sizes of PBM503 and PBM565.

Motor Option Combination Table



Motor Option Combination Table					
Motor No.			Gear Box	Harmonic Gear	Electromagnetic Brake
PBM282F	E20 / PBM282D	A20			
PBM284F	E20 / PBM284D	A20	x	x	
PBM423F	E20 / PBM423D	A20			
PBM603F	E20 / PBM603D	A20			
PBM604F	E20 / PBM604D	A20	x	x	

Motor Standard Specifications (common to all models)

Motor No.	PBM423F, PBM603F, PBM604F, PBM861F, PBM862F	PBM282D, PBM282F, PBM284D, PBM284F, PBM423D, PBM603D, PBM604D
Insulation class	Class B (130)	
Withstand Voltage *	AC1500V 50 / 60Hz 1minute	AC500V 50 / 60Hz 1minute
Insulation resistance *	DC500V 100MΩMIN.	
Degrees of protection	IP40	
Vibration resistance	15 G (Frequency range 10 to 70Hz amplitude 0.060inch 70 to 2000 acceleration 15G)	
Impact resistance	30G(half sine wave with 11 ms duration) The x, y and z are each tested three times for each direction for a total of 18 tests.	
Ambient temperature	-10 to + 40 (Harmonic Gear Model 0 to + 40)	
Ambient humidity	20 to 90%RH (No Condensation)	

* The user should not test the insulation resistance or insulation withstand voltage, because a capacitor has been inserted between the encoder output groundline and the frame to prevent noise.

Features and Functions

Type R

Type P

Type M

Type R Multi-Axis

General Specifications

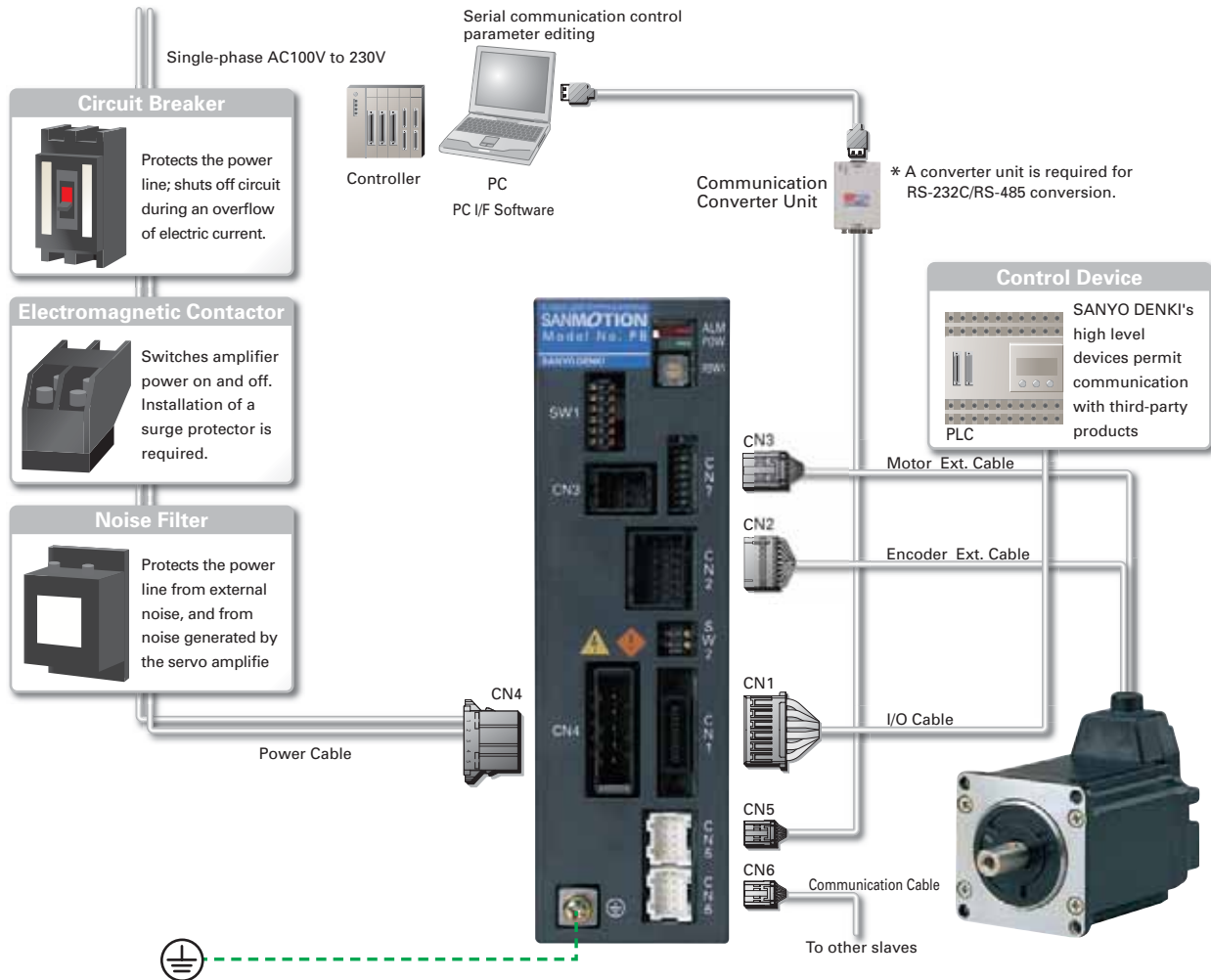
Motor Dimensional Drawings

Options

Model No. PB Type R Single-Axis Type

AC Power Input Type

System Configuration

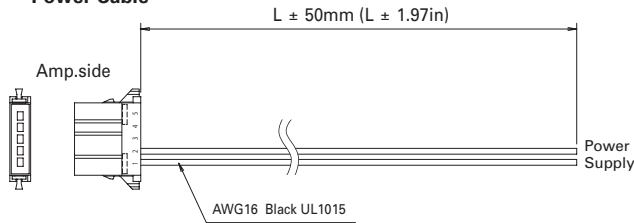


Options

Cable Type	Standard Model Number (Length)	Connector Set Model Number	Maximum Length	Remarks
Power Cable	PBC7P0010A 1m (39.37in)	PBC7P0000A	2m (78.74 in)	-
Motor Ext. Cable	PBC6M0030A 3m (118.11in)	PBC6M0000A	20m (787.40 in)	Use when an extension of 50cm (19.69in) or more is required.
Encoder Ext. Cable	PBC6E0030A 3m (118.11in)	PBC6E0000A	20m (787.40 in)	Use when an extension of 50cm (19.69in) or more is required.
I/O Cable (unshielded)	PBC1S0010A 1m (39.37in)	PBC1S0000A	2m (78.74 in)	-
Communication Cable	PBC6C0003A 30cm (11.81in)	PBC6C0000A	100m (3937.01 in)	Use when multiple axes are connected in a daisy-chain configuration for communication.
Communication Converter Unit	PBFM-U5	Main Body Model.No : 232485CFP01-01 Cable Model.No : PBC4T0005A		RS-232C / RS-485 Converter Unit Converter unit and cable set model
PC I/F Software	SPBA1W-01	-	-	Software for operational check and parameter setting

Optional Cable

Power Cable

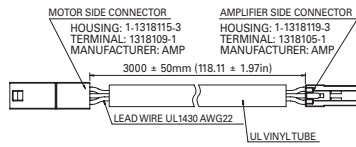


PIN No.	LEAD COLOR	
1	Black	AC1
2	Black	AC2
3		
4		
5		

Connector Set : PBC7P0000A

Manufacturer	Type	Qty.
AMP	Housing : 1-178288-5	1
	Contact : 1-175218-5	5

Motor Ext. Cable



Connector Connection Of Motor Side

PIN No.	LEAD COLOR	
A1	Blue	Motor Lead Wire
B1	Orange	Motor Lead Wire
A2	Red	Motor Lead Wire
B2	Yellow	Motor Lead Wire
A3	White	Brake Lead Wire
B3	Black	Brake Lead Wire

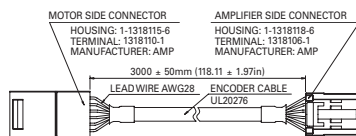
Connector Connection Of Amplifier Side

PIN No.	LEAD COLOR	
1(A1)	Blue	Motor Lead Wire
2(B1)	Orange	Motor Lead Wire
3(A2)	Red	Motor Lead Wire
4(B2)	Yellow	Motor Lead Wire
5(A3)	White	Brake Lead Wire
6(B3)	Black	Brake Lead Wire

Connector Set : PBC6M0000A

Manufacturer	Type	Qty.
AMP	Housing : 1-1318115-3	1
	Terminal : 1318109-1	6
	Housing : 1-1318119-3	1
	Terminal : 1318105-1	6

Encoder Ext. Cable



Connector Connection Of Motor Side

PIN No.	LEAD COLOR	
A1	Blue	CHANNEL A
B1	Brown	CHANNEL A
A2	Green	CHANNEL B
B2	Purple	CHANNEL B
A3	White	CHANNEL C
B3	Yellow	CHANNEL C
A4	Red	+5V
B4	Black	0V
A5	N.C.	
B5	Orange	OVER HEAT
A6	Black	Shield
B6	N.C.	

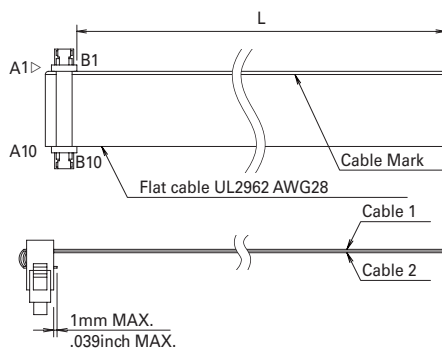
Connector Connection Of Amplifier Side

PIN No.	LEAD COLOR	
1(A1)	Blue	CHANNEL A
2(B1)	Brown	CHANNEL A
3(A2)	Green	CHANNEL B
4(B2)	Purple	CHANNEL B
5(A3)	White	CHANNEL C
6(B3)	Yellow	CHANNEL C
7(A4)	Red	+5V
8(B4)	Black	0V
9(A5)	N.C.	
10(B5)	Orange	OVER HEAT
11(A6)	Black	Shield
12(B6)	N.C.	

Connector Set : PBC6E0000A

Manufacturer	Type	Qty.
AMP	Housing : 1-1318115-6	1
	Terminal : 1318110-1	10
	Housing : 1-1318118-6	1
	Terminal : 1-1318106-1	10

I/O Cable (unshielded)



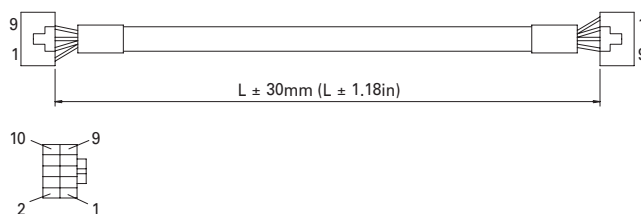
Cable Connection

Cable 1	Cable 2
A1-No.1	B1-No.11
A2-No.2	B2-No.12
A3-No.3	B3-No.13
A4-No.4	B4-No.14
A5-No.5	B5-No.15
A6-No.6	B6-No.16
A7-No.7	B7-No.17
A8-No.8	B8-No.18
A9-No.9	B9-No.19
A10-No.10	B10-No.20

Connector Set : PBC1S0000A

Manufacturer	Type	Qty.
KEL	CONNECTOR : 8822E-020-171D	1

Communication Cable



Connector relay cable

Signal Name	CNA Pin.No.	Color	CNB Pin.No.	Signal Name
A	1	Yellow	1	A
B	2	White	2	B
(V)	3	Brown	3	(V)
(Z)	4	Blue	4	(Z)
GND	5	Black	5	GND
Vcc	6	Red	6	Vcc
—	7	Purple	7	—
—	8	Green	8	—
—	9	—	9	—
FG	10	Drain	10	FG

Connector Set : PBC6C0000A

Manufacturer	Type	Qty.
JST	Housing : PADP-10V-1-S	2
	Contact : SPH-002T-P0.5L	20

Features and Functions

Type R

Type P

Type M

Type R Multi-Axis

General Specifications

Motor Dimensional Drawings

Options

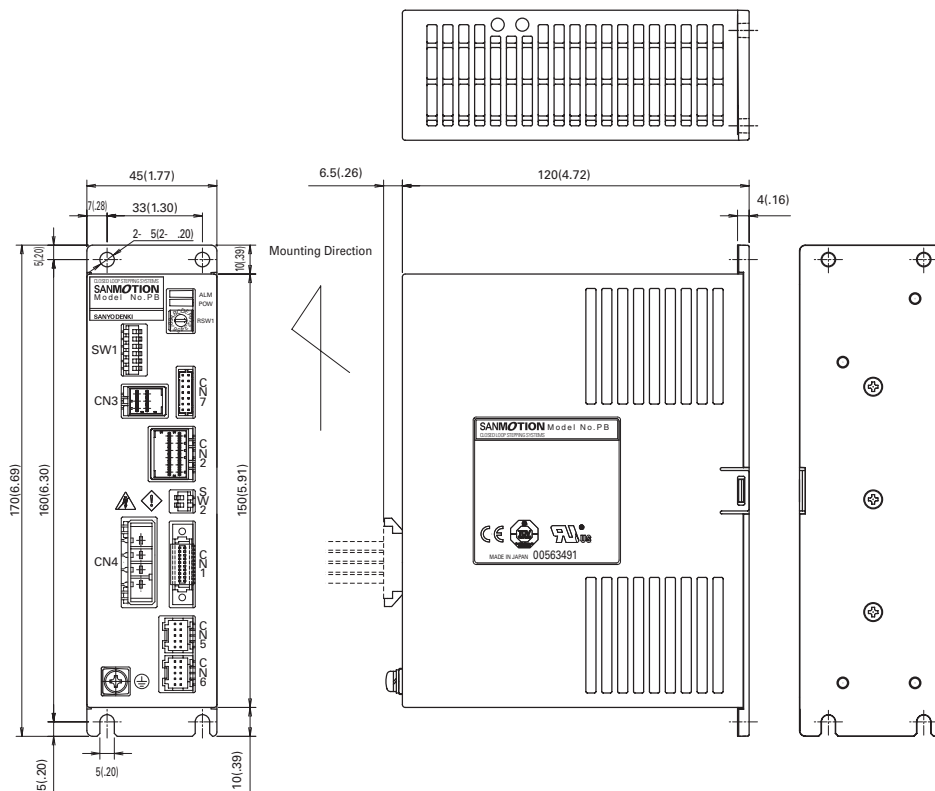
Model No. PB Type R Single-Axis Type

AC Power Input Type

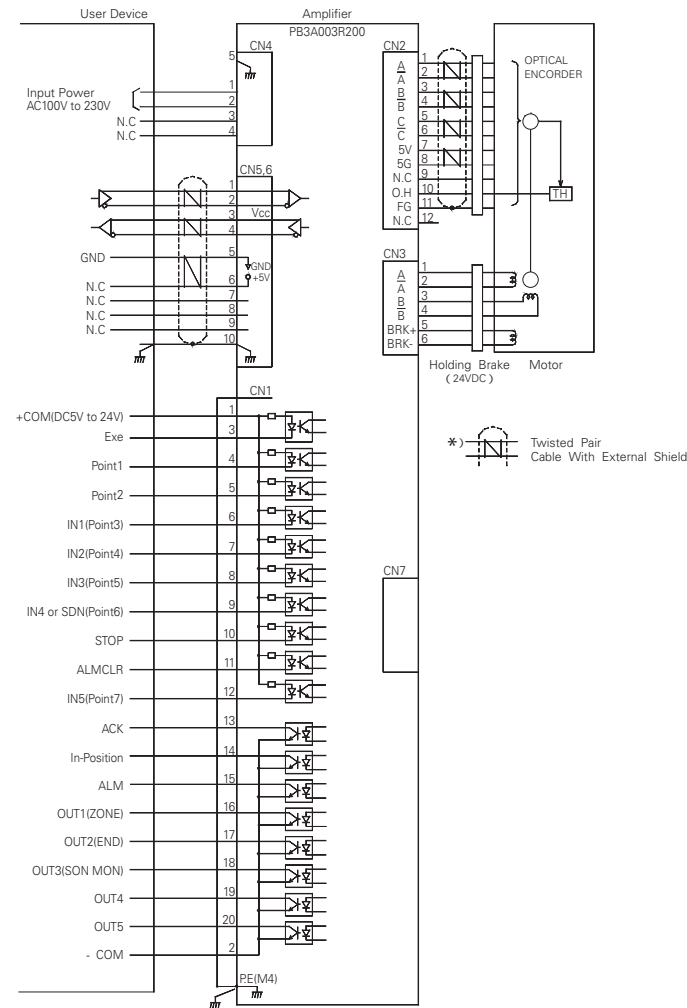
General Specifications

Amplifier Model		PB3A003R200
Control Mode		PWM Control SIN drive method
Power Supply	Single Power	AC100V to 230V -15% +10% 50 / 60Hz
Environment	Ambient temp.	0 to 55
	Operating Storage	-20 to 70
	Operating/Storage Humidity	Maximum 90% RH (non-condensing)
	Vibration Resistance	0.5G (tested with frequency range 10 to 55 Hz, X, Y, Z each direction 2H)
Structure		Tray structure Rear mounting type
Mass (Weight) / Dimensions		Approx. 0.8kg (28.22oz)/ W45×H150×D120mm (W1.77×H5.91×D4.72inch)
Functions	Rotation Speed	0 to 4500min ⁻¹ (4000min ⁻¹ is used for an 86mm-square motor)
	Resolution (P/R)	500, 1000, 2000, 4000, 5000, 10000
	Regeneration Process	Internal (external regeneration available)
	Protective Functions	Encoder Disconnection, Encoder Counter Error, Power Voltage Error, Initialization Error, Position Deviation Error, Over-speed, Regeneration Voltage Error, Zero-return Error, Absolute position sign reversal, Deviation Counter Overflow, Motor Overheat, Amplifier Overheat, Internal voltage Error, Over-current, CPU Error
	LED Display	Power status, Alarm (flashing indicator)
	Operation Functions	Normal Drive (incremental move command, absolute move command), Zero-return, Module Operation, Push Operation
	Switch	DIP SW1: Transmission Speed Setting (9600, 38400, 115200, 128000bps) DIP SW2: Terminating Resistor Setting RSW : Node Address Setting (0 to F)
Input/Output Signals	Input Signals	Fixed function (2) : EXE, Point, ALMCLR, STOP Selectable (5) : Point, Pause, Interlock, SELECT, Generic Input, HOME, Hard Limit
	Output Signals	CN1 Fixed function (2) : ALM, In-Position, Ack Selectable (5) : ZONE, END, Busy, HEND, SON MON, Generic Input, Input Monitor
	Communication Specifications	RS-485 Standard Start-Stop Synchronization, Full Duplex Trans. Speed: 9600, 38400, 115200, 128000bps

Amplifier Dimensional Drawing [Unit : mm (inch)]



External Wiring Diagram

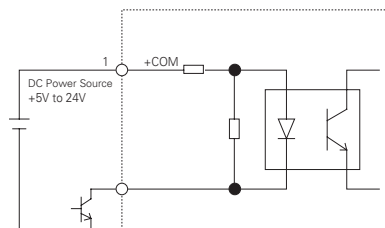


Note 1: The CN1 general-purpose input / output signal function is selected through communication.
 Please see the basic specifications for details.

Input / Output Signals Circuit

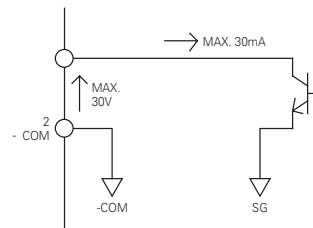
Generic Input

Input Voltage Specifications : DC5V to 24V±10%



Generic Output

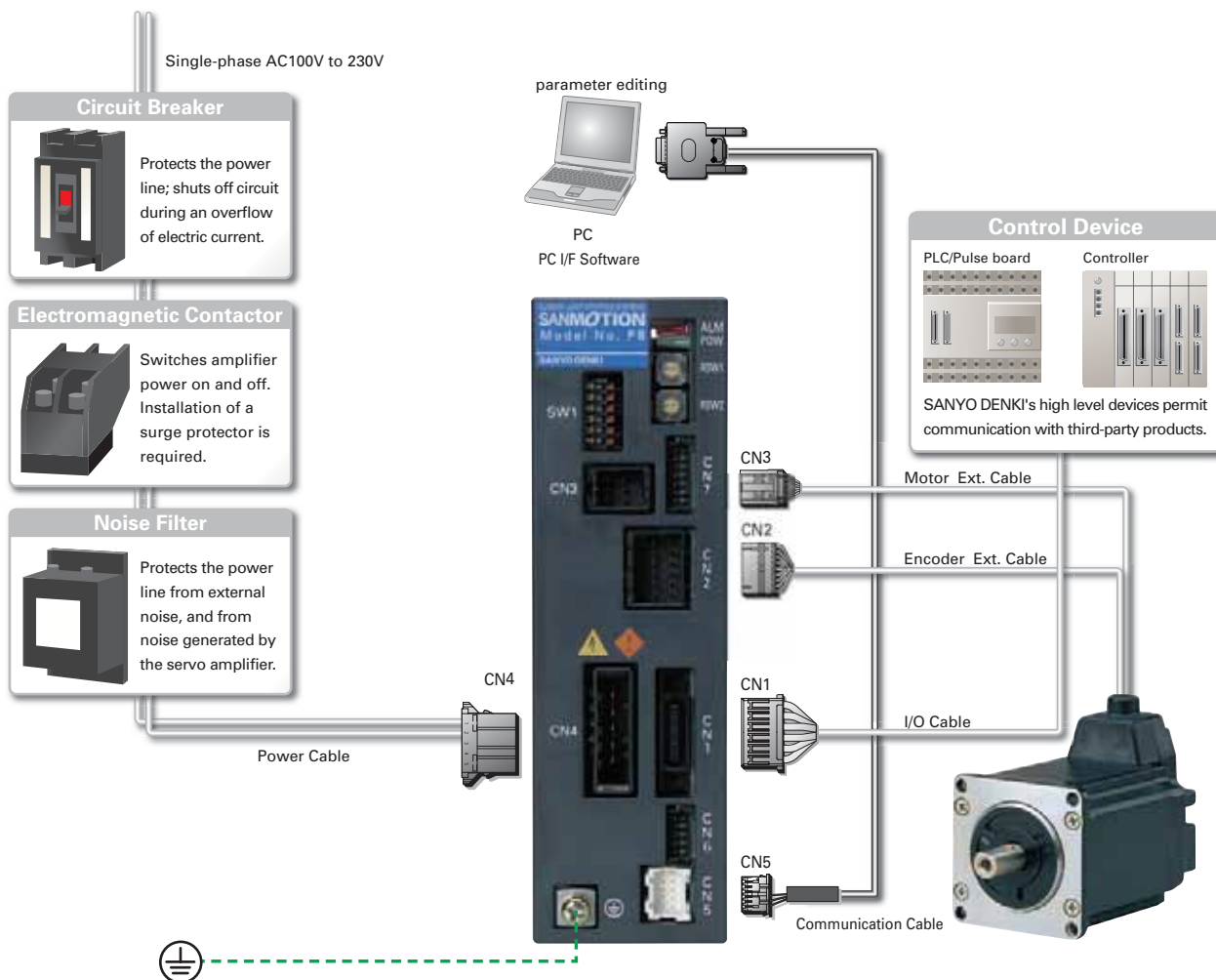
Output Current : 30mA MAX.



Model No. PB Type P

AC Power Input Type

System Configuration

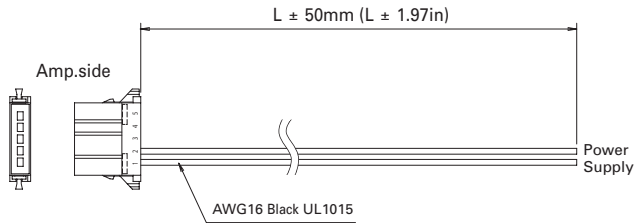


Options

Cable Type	Standard Model Number (Length)	Connector Set Model Number	Maximum Length	Remarks
Power Cable	PBC7P0010A 1m (39.37in)	PBC7P0000A	2m (78.74 in)	-
Motor Ext. Cable	PBC6M0030A 3m (118.11in)	PBC6M0000A	20m (787.40 in)	Use when an extension of 50cm (19.69in) or more is required.
Encoder Ext. Cable	PBC6E0030A 3m (118.11in)	PBC6E0000A	20m (787.40 in)	Use when an extension of 50cm (19.69in) or more is required.
I/O Cable (shielded)	PBC1S0010C 1m (39.37in)	PBC1S0000A	2m (78.74 in)	-
Communication Cable (Dsub9pin)	PBC5C0010A 1m (39.37in)	-	-	Dedicated cable for RS-232C communications
Communication Converter Unit	Not required	-	-	-
PC I/F Software	SPBA1W-01	-	-	Software for operational check and parameter setting

Optional Cable

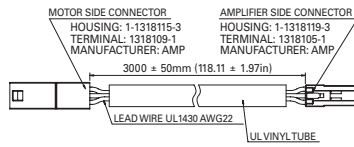
Power Cable



PIN No.	LEAD COLOR	
1	Black	AC1
2	Black	AC2
3		
4		
5		

Connector Set : PBC7P0000A		
Manufacturer	Type	Qty.
AMP	Housing : 1-178288-5	1
	Contact : 1-175218-5	5

Motor Ext. Cable

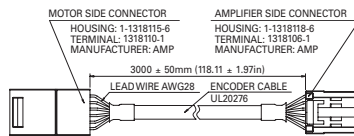


PIN No.	LEAD COLOR	
A1	Blue	Motor Lead Wire
B1	Orange	Motor Lead Wire
A2	Red	Motor Lead Wire
B2	Yellow	Motor Lead Wire
A3	White	Brake Lead Wire
B3	Black	Brake Lead Wire

PIN No.	LEAD COLOR	
1(A1)	Blue	Motor Lead Wire
2(B1)	Orange	Motor Lead Wire
3(A2)	Red	Motor Lead Wire
4(B2)	Yellow	Motor Lead Wire
5(A3)	White	Brake Lead Wire
6(B3)	Black	Brake Lead Wire

Connector Set : PBC6M0000A		
Manufacturer	Type	Qty.
AMP	Housing : 1-1318115-3	1
	Terminal : 1318109-1	6
	Housing : 1-1318119-3	1
	Terminal : 1318105-1	6

Encoder Ext. Cable

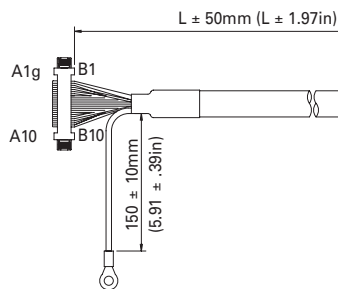


PIN No.	LEAD COLOR	
A1	Blue	CHANNEL A
B1	Brown	CHANNEL A
A2	Green	CHANNEL B
B2	Purple	CHANNEL B
A3	White	CHANNEL C
B3	Yellow	CHANNEL C
A4	Red	+5V
B4	Black	0V
A5	N.C.	
B5	Orange	OVER HEAT
A6	Black	Shield
B6	N.C.	

PIN No.	LEAD COLOR	
1(A1)	Blue	CHANNEL A
2(B1)	Brown	CHANNEL A
3(A2)	Green	CHANNEL B
4(B2)	Purple	CHANNEL B
5(A3)	White	CHANNEL C
6(B3)	Yellow	CHANNEL C
7(A4)	Red	+5V
8(B4)	Black	0V
9(A5)	N.C.	
10(B5)	Orange	OVER HEAT
11(A6)	Black	Shield
12(B6)	N.C.	

Connector Set : PBC6E0000A		
Manufacturer	Type	Qty.
AMP	Housing : 1-1318115-6	1
	Terminal : 1318110-1	10
	Housing : 1-1318118-6	1
	Terminal : 1-1318106-1	10

I/O Cable (shielded)



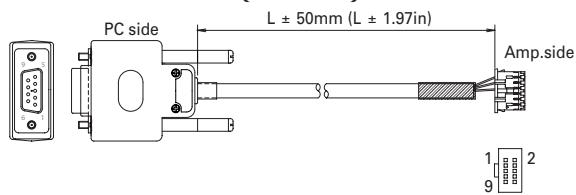
CN1 Wiring

CN1 PIN No.	Mark Display	Mark	LINE COLOR
A1		Red	Orange
A2		Black	
A3		Red	Gray
A4		Black	
A5		Red	
A6		Black	White
A7		Red	
A8		Black	Yellow
A9		Red	
A10		Black	Pink

CN1 PIN No.	Mark Display	Mark	LINE COLOR
B1		Red	Orange
B2		Black	
B3		Red	Gray
B4		Black	
B5		Red	White
B6		Black	
B7		Red	
B8		Black	Yellow
B9		Red	
B10		Black	Pink

Connector Set : PBC1S0000A		
Manufacturer	Type	Qty.
KEL	Connector : 8822E-020-171D	1
	Crimp Contact : V1.25-M4	
	Drain Wire : UL1007 20AWG	
	Cable : UL20276-28AWG	

Communication Cable (Dsub 9Pin)



Connector relay cable

PC Side Pin No.	Signal Name	Amp Side Pin No.	Signal Name
1	N.C.	1	RXD
2	RXD	2	TXD
3	TXD	3	N.C.
4	N.C.	4	N.C.
5	GND	5	GND
6	N.C.	6	N.C.
7	N.C.	7	N.C.
8	N.C.	8	N.C.
9	N.C.	9	N.C.
		10	Shield

※Without connector set

Features and Functions

Type R

Type P

Type M

Type R Multi-Axis

General Specifications

Motor Dimensional Drawings

Options

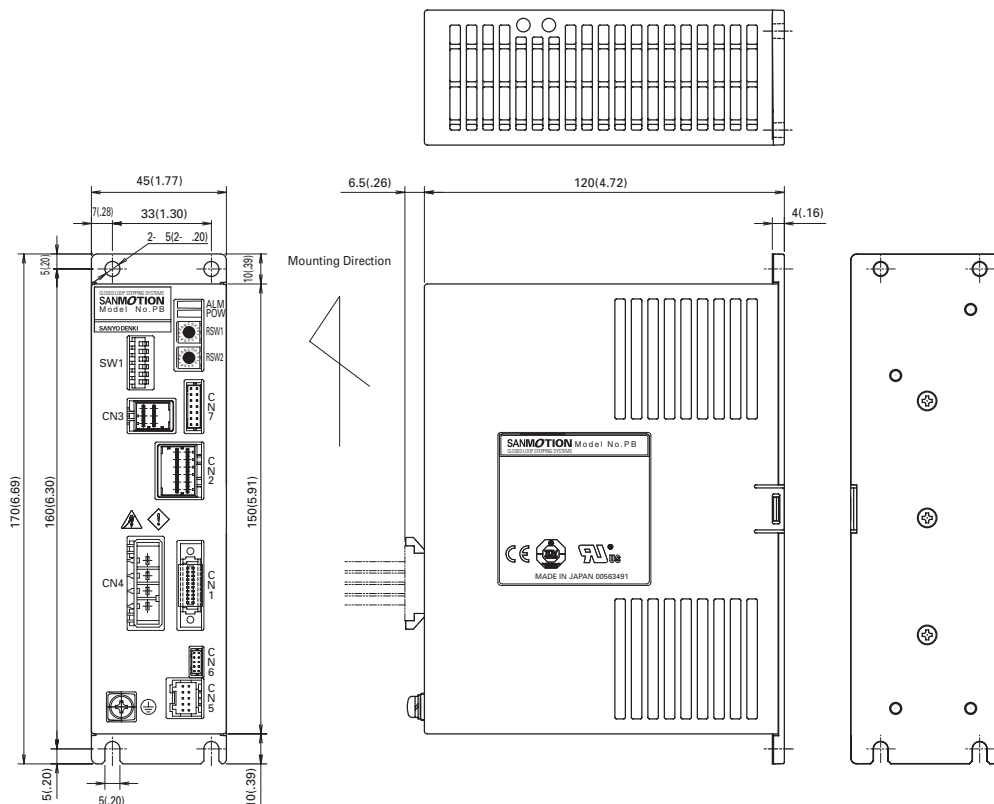
Model No. PB Type P

AC Power Input Type

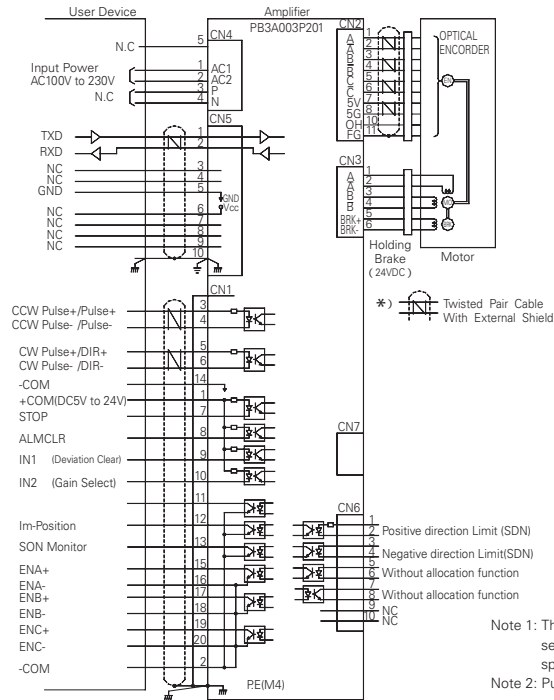
General Specifications

Amplifier Model			PB3A003P201, PB3A003P202
Control Mode			PWM Control SIN drive method
Power Supply	Single Power		AC100V to 230V –15% +10% 50 / 60Hz
Environment	Ambient temp.	Operating	0 to 55
		Storage	–20 to 70
	Operating/ Storage Humidity		Maximum 90% RH (non-condensing)
	Vibration Resistance		0.5G (tested with frequency range 10 to 55 Hz, X, Y, Z each direction 2H)
Structure			Tray structure Rear mounting type
Mass (Weight)/ Dimensions			Approx. 0.8kg (28.22oz)/ W45×H150×D120mm (W1.77×H5.91×D4.72inch)
Functions	Rotation Speed		0 to 4500min ^{–1} (4000min ^{–1} is used for an 86mm-square motor)
	Resolution (P/R)		500, 1000, 2000, 4000, 5000, 10000
	Regeneration Process		Internal(external regeneration available)
	Protective Functions		Encoder Disconnection, Encoder Counter Error, Power Voltage Error, Initialization Error, Position Deviation Error, Over-speed,Regeneration Voltage Error, Zero-return Error, Absolute position sign reversal, Deviation Counter Overflow, Motor Overheat, Amplifier Overheat, Internal voltage Error, Over-current, CPU Error
	LED Display		Power status, Alarm(flashing indicator)
	Functions		Normal Drive, Zero-return, S-shape Acceleration / Deceleration Drive
	Switch		DIP SW1: Pulse Input Type Select(ON: 2 Input OFF: 1 Input) DIP SW2, 3: Resolution Selection (500, 1000, 5000, 10000P/R) 2000 and 4000 division resolution modes are selected via communication DIP SW 4 to 6: Motor Select RSW1: Normalize velocity loop gain setting RSW2: S-Shape filter potentiometer setting
Input/ Output Signals	Input Signals		Pulse, Deviation Clear, HOME, Hard.Limit, STOP, ALMCLR
	Output Signals		SON Monitor, ALM, Zero-return completion,In-Position, Encoder Signal Output
	Communication Specifications		RS-232C(For parameter setting) Trans. Speed : 9600bps

Amplifier Dimensional Drawing [Unit : mm(inch)]



External Wiring Diagram

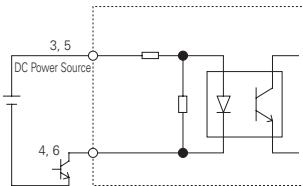


Input / Output Signals Circuit

PB3A003P201

Pulse Input

Input Voltage Specifications : DC5V±10%

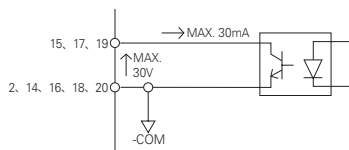


In case the voltage is at 5V MIN.
Insert a resistor "R" which satisfies " $(\text{Input Voltage} - 1V) / (270 + R) = 10 \text{ mA}$ "

Line driver input permitted

Encoder Signal Output

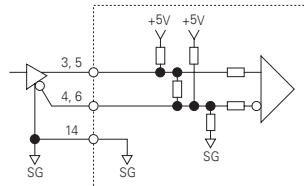
Collector Voltage: DC30V MAX.
Output Current : 30mA MAX.



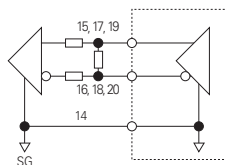
PB3A003P202

Pulse Input

Pulse Input : 250kpps MAX.



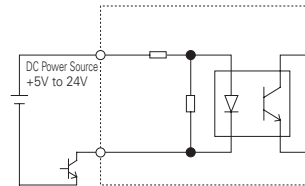
Encoder Signal Output



PB3A003P201/202

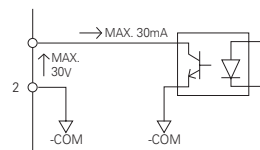
Generic Input / Limit Input

Input Voltage Specifications : DC5V to 24V±10%



Generic Output

Collector Voltage: DC30V MAX.
Output Current : 30mA MAX.



Features and Functions

Type R

Type P

Type M

Type R Multi-Axis

General Specifications

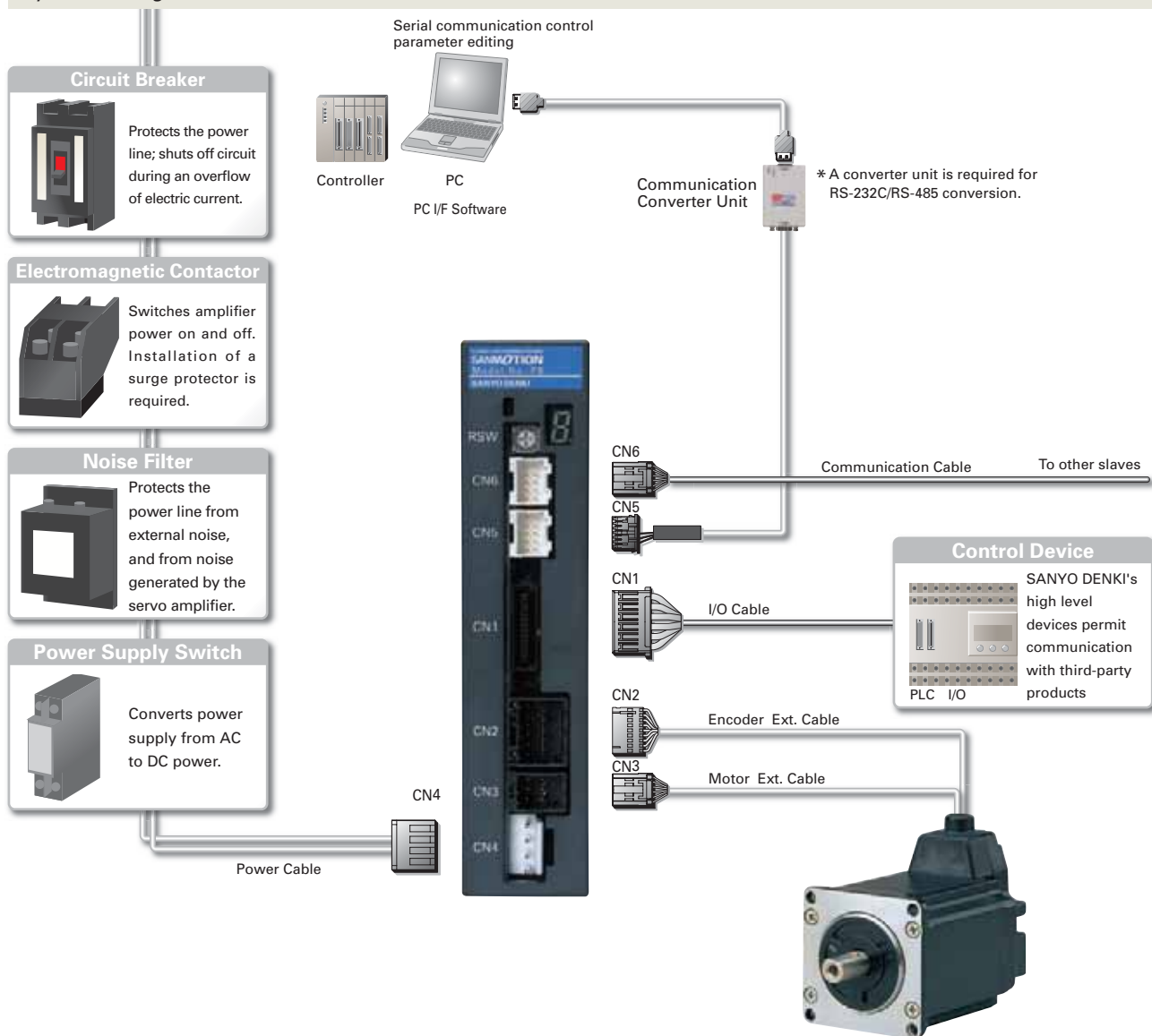
Motor Dimensional Drawings

Options

Model No. PB Type M

DC Power Input Type

System Configuration

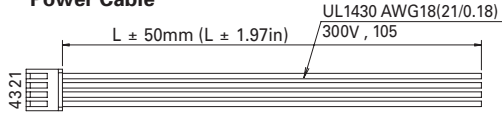


Options

Cable Type	Standard Model Number (Length)	Connector Set Model Number	Maximum Length	Remarks
Power Cable	PBC6P0010A 1m (39.37in)	PBC6P0000A	2m (78.74 in)	-
Motor Ext. Cable	PBC6M0030A 3m (118.11in)	PBC6M0000A	20m (787.40 in)	Use when an extension of 50cm(19.69in) or more is required.
Encoder Ext. Cable	PBC6E0030A 3m (118.11in)	PBC6E0000A	20m (787.40 in)	Use when an extension of 50cm(19.69in) or more is required.
I/O Cable (unshielded)	PBC5S0010A 1m (39.37in)	PBC5S0000A	2m (78.74 in)	-
I/O Cable (shielded)	PBC5S0010C 1m (39.37in)	PBC5S0000A	2m (78.74 in)	Use for pulse input
Communication Cable (to Amp.)	PBC6C0003A 30cm (11.81in)	PBC6C0000A	100m (3937.01 in)	Use when multiple axes are connected in a daisy-chain configuration for communication.
Communication Converter Unit	PBFM-U5	Main Body Model.No : 232485CFP01-01 Cable Model.No : PBC4T0005A	RS-232C / RS-485 Converter Unit Converter unit and cable set model	
PC I/F Software	SPBAIW01	-	-	Software for operational check and parameter setting

Optional Cable

Power Cable



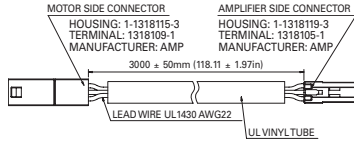
Connector Connection Of Amplifier Side

PIN No.	LEAD COLR	Signal Name
1	Red	DC+24/48V
2	Blue	GND
3	Yellow	
4	Green	FG

Connector Set : PBC6P0000A

Manufacturer	Type	Qty.
JST	Connector : VHR-4N Contact : SVH-21T-P1.1	1 4
Appropriate electric wire : AWG#22-18		

Motor Ext. Cable



Connector Connection Of Motor Side

PIN No.	LEAD COLR	
A1	Blue	Motor Lead Wire
B1	Orange	Motor Lead Wire
A2	Red	Motor Lead Wire
B2	Yellow	Motor Lead Wire
A3	White	Brake Lead Wire
B3	Black	Brake Lead Wire

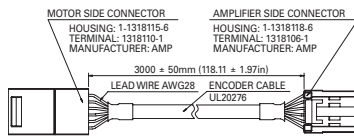
Connector Connection Of Amplifier Side

PIN No.	LEAD COLR	
1(A1)	Blue	Motor Lead Wire
2(B1)	Orange	Motor Lead Wire
3(A2)	Red	Motor Lead Wire
4(B2)	Yellow	Motor Lead Wire
5(A3)	White	Brake Lead Wire
6(B3)	Black	Brake Lead Wire

Connector Set : PBC6M0000A

Manufacturer	Type	Qty.
AMP	Housing : 1-1318115-3	1
	Terminal : 1318109-1	6
	Housing : 1-1318119-3	1
	Terminal : 1318105-1	6

Encoder Ext. Cable



Connector Connection Of Motor Side

PIN No.	LEAD COLR	
A1	Blue	CHANNEL A
B1	Brown	CHANNEL A
A2	Green	CHANNEL B
B2	Purple	CHANNEL B
A3	White	CHANNEL C
B3	Yellow	CHANNEL C
A4	Red	+5V
B4	Black	0V
A5	N.C.	
B5	Orange	OVER HEAT
A6	Black	Shield
B6	N.C.	

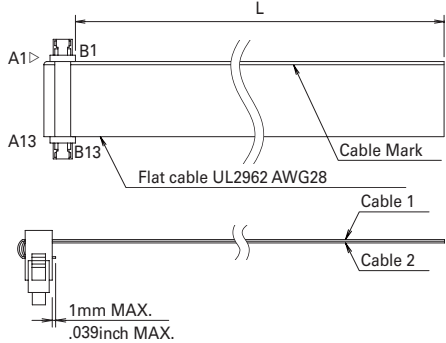
Connector Connection Of Amplifier Side

PIN No.	LEAD COLR	
1(A1)	Blue	CHANNEL A
2(B1)	Brown	CHANNEL A
3(A2)	Green	CHANNEL B
4(B2)	Purple	CHANNEL B
5(A3)	White	CHANNEL C
6(B3)	Yellow	CHANNEL C
7(A4)	Red	+5V
8(B4)	Black	0V
9(A5)	N.C.	
10(B5)	Orange	OVER HEAT
11(A6)	Black	Shield
12(B6)	N.C.	

Connector Set : PBC6E0000A

Manufacturer	Type	Qty.
AMP	Housing : 1-1318115-6	1
	Terminal : 1318110-1	10
	Housing : 1-1318118-6	1
	Terminal : 1318106-1	10

I/O Cable (unshielded)



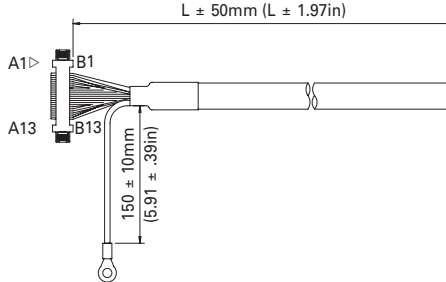
Cable Connection

Cable 1	Cable 2
A1-No.1	B1-No.14
A2-No.2	B2-No.15
A3-No.3	B3-No.16
A4-No.4	B4-No.17
A5-No.5	B5-No.18
A6-No.6	B6-No.19
A7-No.7	B7-No.20
A8-No.8	B8-No.21
A9-No.9	B9-No.22
A10-No.10	B10-No.23
A11-No.11	B11-No.24
A12-No.12	B12-No.25
A13-No.13	B13-No.26

Connector Set : PBC5S0000A

Manufacturer	Type	Qty.
KEL	Connector : 8822E-026-171D	1

I/O Cable (shielded)



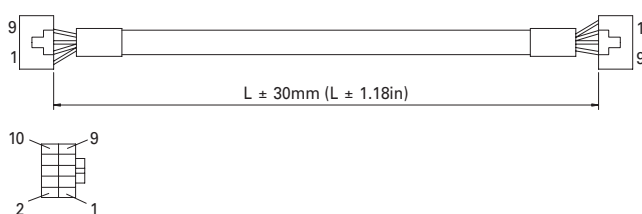
CN Wiring

CN1 Pin.No.	Signal Name	Mark	LINE COLR	CN1 Pin.No.	Signal Name	Mark	LINE COLR
A1		Red	Orange	B1		Black	Gray
A2		Black		B2		Red	White
A3		Red		B3		Black	
A4		Black	Gray	B4		Red	
A5		Red		B5		Black	Yellow
A6		Black	White	B6		Red	Pink
A7		Red		B7		Black	
A8		Black	Yellow	B8		Red	Orange
A9		Red		B9		Black	
A10		Black	Pink	B10		Red	Gray
A11		Red		B11		Black	
A12		Black	Orange	B12		Red	White
A13		Red	Gray	B13		Black	

Connector Set : PBC5S0000A

Manufacturer	Type	Qty.
KEL	Connector : 8822E-026-171D	1
	Crimp Contact : V1.25-M4	
	Drain Wire : UL1007 20AWG	
	Cable : UL20276-28AWG	

Communication Cable (Dsub 9 Pin)



Connector relay cable

Signal Name	CNA Pin.No.	CNB Pin.No.	Signal Name
A	1	Yellow	1
B	2	White	2
(Y)	3	Brown	3
(Z)	4	Blue	4
GND	5	Black	5
Vcc	6	Red	6
—	7	Purple	7
—	8	Green	8
—	9	Drain	9
FG	10		10

Connector Set : PBC6C0000A

Manufacturer	Type	Qty.
JST	Housing : PADP-10V-1-S Contact : SPH-002T-P0.5L	2 20

Features and Functions

Type R

Type P

Type M

Type R Multi-Axis

General Specifications

Motor Dimensional Drawings

Options

Model No. PB Type M

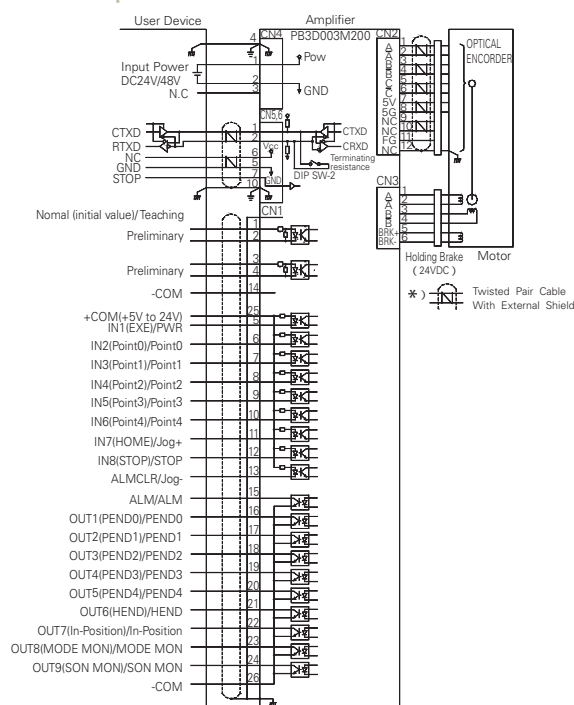
DC Power Input Type

General Specifications

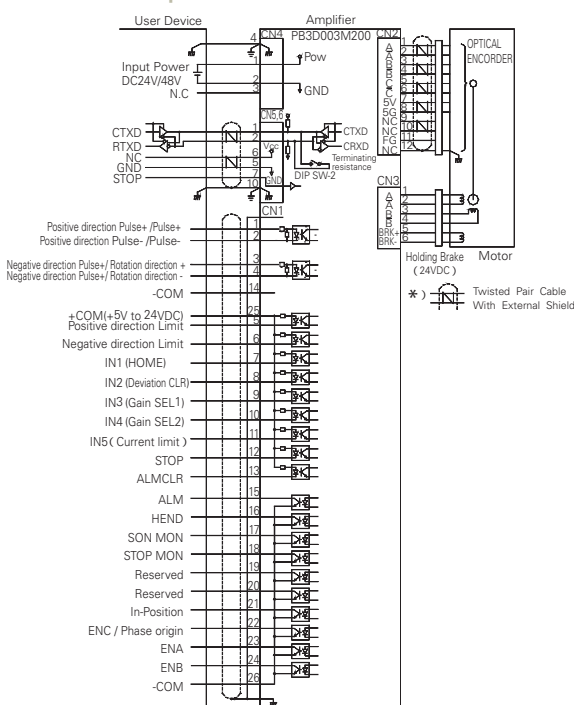
Amplifier Model		PB3D003M200	
Interface		Generic Input(SW1=ON)	Pulse Train Input(SW1 = OFF)
Control Mode		PWM Control SIN drive method	
Power Supply	Single Power	DC24V / 48V $\pm 10\%$ (28mm [1.10inch] Motor is only available as 24V.)	
Environment	Ambient temp.	Operating	0 to 55
		Storage	-20 to 70
	Operating/Storage Humidity	Maximum 90% RH (non-condensing)	
	Vibration Resistance	0.5G (tested with frequency range 10 to 55 Hz, X, Y, Z each direction 2H)	
Mass (Weight) / Dimensions		Approx. 0.36kg (12.70oz) / W32xH160xD95mm (W1.26xH6.30xD3.74inch)	
Functions	Rotation Speed	0 to 4500min ⁻¹	
	Resolution (P/R)	500, 1000, 2000, 4000, 5000, 10000	
	Regeneration Process	Built-in	
	Protective Functions	Power Voltage Error, Regeneration Voltage Error, Over-speed, Encoder Disconnection, CPU Error, Overload Stop, Excessive Position Deviation, Zero-return Error, Nonvolatile Memory Error, Initialization Error (Power Line Disconnection)	
	Display	7SEG LED Display	
	Functions	Normal Drive(incremental move , absolute move) , Zero-return, Module Operation, Push Operation, Teaching Functions Point Functions: 128Point Program Functions: 1PRGx1024Line 32PRGx32Line 128PRGx8Line	Normal Drive, Zero-return
	Rotary Switch	Node Address Setting (0 to F)	Normalize velocity loop gain setting
	DIP-Switches	SW1 : Interface Selection (On: RS-485, OFF: Pulse) SW2 : Terminating Resistor Setting (On: with terminating resistance)	
Input/ Output Signals	Input Signals	(Normal Mode) STOP, EXE, POINT, HOME, JOG, SELECT, Pause, Interlock, Generic Input, MODE SELECT, Hard Limit, ALM CLR (Teaching Mode) STOP, JOG, Point, PWR	Pulse, STOP, ALMCLR, Gain Setting, Deviation Clear, HOME
	Output Signals	(Normal Mode) Ack, PEND, END, Busy, Zone, Mode MON, STOP MON, In-Position, Homing complete, Generic Output, Encoder Output, Input Monitor (Teaching Mode) PEND, HEND, In-Position, Mode MON, SON MON	ALM, STOP MON, In-Position, Homing complete, Encoder Output, SON MON, STOP MON
	Communication Specifications	RS-485 Standard Start-Stop Synchronization, Full Duplex	
	Trans. Speed	9600, 38400, 115200, 128000bps	9600bps

External Wiring Diagram

Generic Input DIP Switch SW1:ON

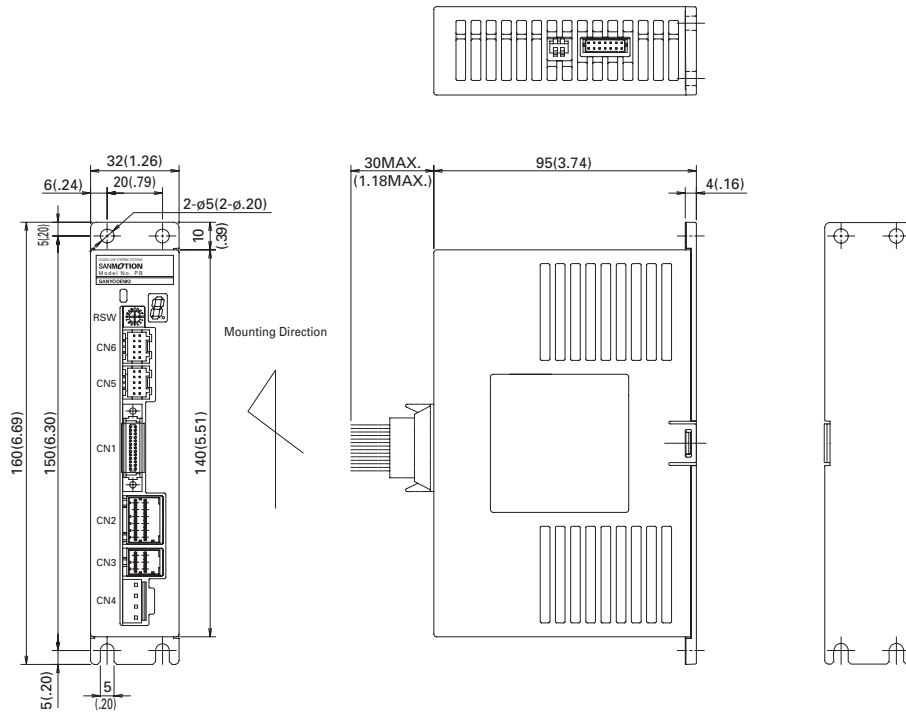


Pulse Stream Input DIP Switch SW1:OFF



Note 1: The CN1 general-purpose input / output signal function is selected through communication. Please see the basic specifications for details.

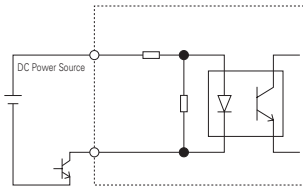
Amplifier Dimensional Drawing [Unit : mm (inch)]



Input/ Output Signals Circuit

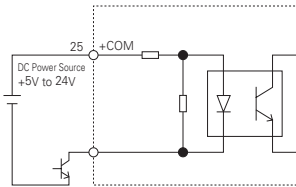
CN1- Pin. No.1,2 / No.3,4

Input Voltage Specifications : DC3V to 5V±10%
Pulse Input : 250kpps MAX.



Generic Input (CN1- Pin.5 to No.13)

Input Voltage Specifications : DC5V to 24V±10%

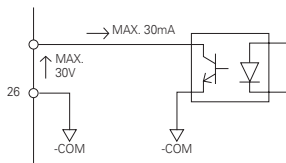


In case the voltage is at 5V MIN.

Insert a resistor 'R' which satisfies $(\text{Input Voltage} - 1V) / (270 + R) = 10 \text{ mA}$

Generic Output

Collector Voltage : DC30V MAX.
Output Current : 30mA MAX.



Features and Functions

Type R

Type P

Type M

Type R Multi-Axis

General Specifications

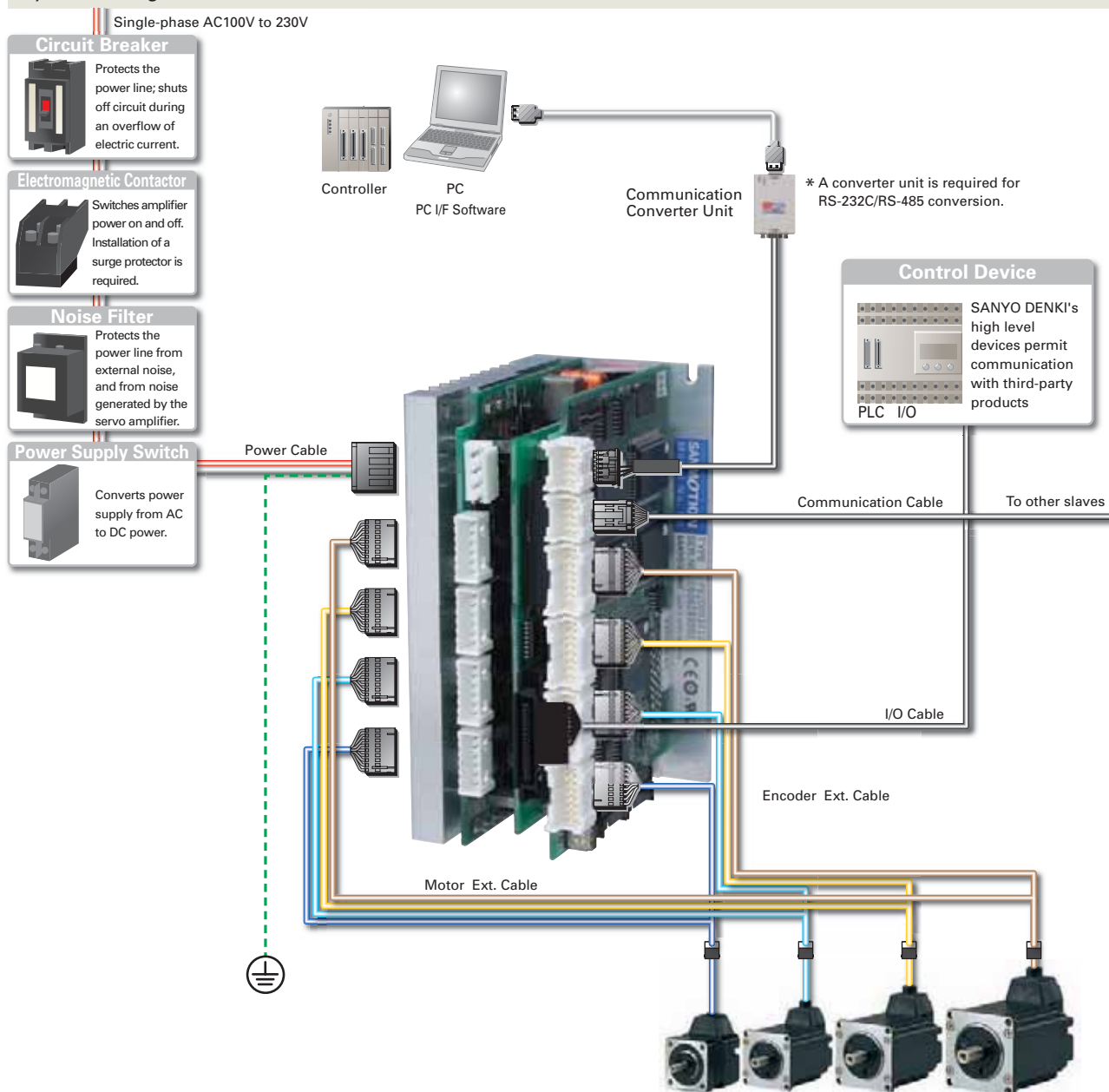
Motor Dimensional Drawings

Options

Model No. PB Type R Multi-Axis Type

DC Power Input Type

System Configuration

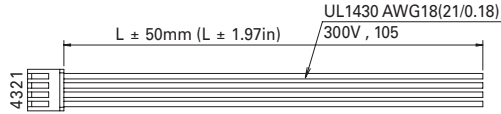


Options

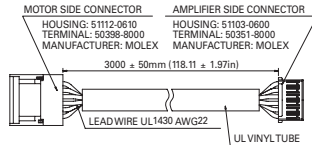
Cable Type	Standard Model Number (Length)	Connector Set Model Number	Maximum Length	Remarks
Power Cable	PBC6P0010A 1m (39.37in)	PBC6P0000A	2m (78.74 in)	-
Motor Cable	PBC4M0030A 3m (118.11in)	PBC4M0000A	20m (787.40 in)	An extension cable is required.
Encoder Cable	PBC5E0030A 3m (118.11in)	PBC5E0000A	20m (787.40 in)	An extension cable is required.
Encoder Cable (with limit sensor input)	PBC5E0030C 3m (118.11in)	PBC5E0000A	20m (787.40 in)	Please specify when using an external limit sensor.
I/O Cable	PBC4S0010A 1m (39.37in)	PBC4S0000A	2m (78.74 in)	-
Communication Cable	PBC4C0003A 30cm (11.81in)	PBC4C0000A	100m (3937.01 in)	Use when multiple axes are connected in a daisy-chain configuration for communication.
Communication Converter Unit	PBFM-U5	Main Body Model.No : 232485CFP01-01 Cable Model.No : PBC4T0005A		RS-232C / RS-485 Converter Unit Converter unit and cable set model
PC I/F Software	SPBR1W-01	-	-	Software for operational check and parameter setting
Regenerative Unit	PBFE-01	-	-	Required if regeneration voltage is more than 40V

Optional Cable

Power Cable



Motor Cable



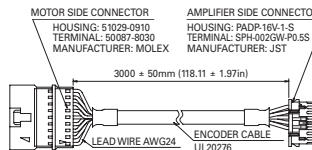
PIN No.	LEAD COLOR	
A1	Blue	Motor Lead Wire
B1	Orange	Motor Lead Wire
A2	Red	Motor Lead Wire
B2	Yellow	Motor Lead Wire
A3	White	Brake Lead Wire
B3	Black	Brake Lead Wire

PIN No.	LEAD COLOR	Signal Name
1	Red	DC+24/48V
2	Blue	GND
3	Yellow	DC+24V *1
4	Green	FG

*Connect only for amplifiers with part numbers ending with "1" or "2"

Manufacturer	Type	Qty.
JST	Connector : VHR-4N	1
	Contact : SVH-21T-P1.1	4
	Appropriate electric wire : AWG422-18	

Encoder Cable

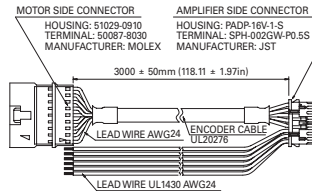


PIN No.	LEAD COLOR	
1	Blue	CHANNEL A
2	Brown	CHANNEL A
3	Green	CHANNEL B
4	Purple	CHANNEL B
5	White	CHANNEL C
6	Yellow	CHANNEL C
7	Red	+5V
8	Black	0V
9	Black	Shield

PIN No.	LEAD COLOR	
1	Blue	CHANNEL A
2	Brown	CHANNEL A
3	Green	CHANNEL B
4	Purple	CHANNEL B
5	White	CHANNEL C
6	Yellow	CHANNEL C
7	Red	+5V
8	Black	0V
9	Black	Shield
10	N.C.	
11	N.C.	
12	N.C.	
13	N.C.	
14	N.C.	
15	N.C.	
16	N.C.	

Manufacturer	Type	Qty.
MOLEX	Housing : 51029-0910	1
	Terminal : 50087-8030	9
JST	Housing : PADP-16V-1-S	1
	Terminal : SPH-002GW-P0.5S	15

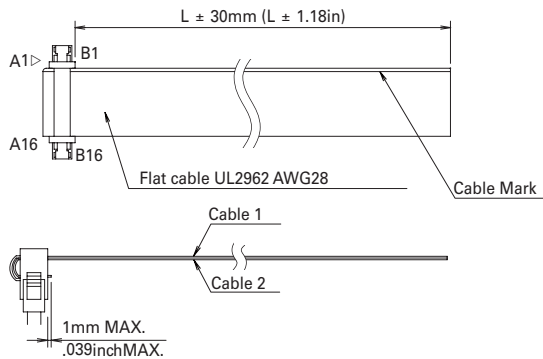
Encoder Cable (with limit sensor input)



PIN No.	LEAD COLOR	
1	Blue	CHANNEL A
2	Brown	CHANNEL A
3	Green	CHANNEL B
4	Purple	CHANNEL B
5	White	CHANNEL C
6	Yellow	CHANNEL C
7	Red	+5V
8	Black	0V
9	Black	Shield

PIN No.	LEAD COLOR	
1	Blue	CHANNEL A
2	Brown	CHANNEL A
3	Green	CHANNEL B
4	Purple	CHANNEL B
5	White	CHANNEL C
6	Yellow	CHANNEL C
7	Red	+5V
8	Black	0V
9	Black	Shield
10	N.C.	
11	Blue	SDN
12	Black	GND
13	Yellow	LIMIT
14	Black	GND
15	Red	Vcc
16	Red	Vcc

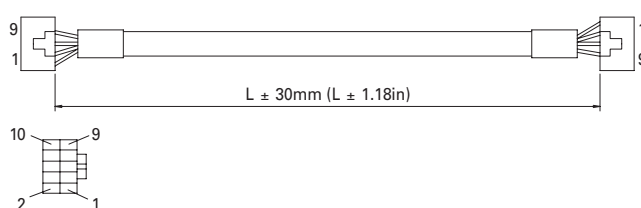
I/O Cable (unshielded)



Cable 1	Cable 2
A1-No.1	B1-No.17
A2-No.2	B2-No.18
A3-No.3	B3-No.19
A4-No.4	B4-No.20
A5-No.5	B5-No.21
.	.
.	.
.	.
A13-No.13	B13-No.29
A14-No.14	B14-No.30
A15-No.15	B15-No.31
A16-No.16	B16-No.32

Manufacturer	Type	Qty.
KEL	Connector : 8822E-032-171D	1

Communication Cable



Signal Name	CNA Pin No.	CNB Pin No.	Signal Name
A	1	1	A
B	2	2	B
(V)	3	3	(V)
(Z)	4	4	(Z)
GND	5	5	GND
Vcc	6	6	Vcc
STOP	7	7	STOP
FG	8	8	FG
—	9	9	—
—	10	10	—

Manufacturer	Type	Qty.
JST	Housing : PADP-10V-1-S	2
	Contact : SPH-002T-P0.5L	20

Features and Functions

Type R

Type P

Type M

Type R Multi-Axis

General Specifications

Motor Dimensional Drawings

Options

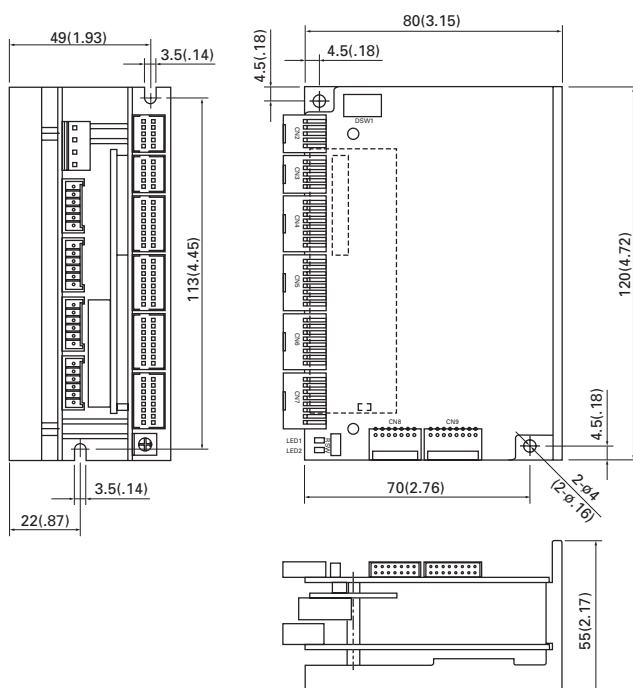
Model No. PB Type R Multi-Axis Type

DC Power Input Type

General Specifications

Amplifier Model		PB2D003R1U
Control Mode		PWM Control Trapezoidal drive method
Power Supply	Main Power Supply	DC24V/36V±10%
	Control Power Supply	DC24V±10% (only for part numbers ending with "1" or "3")
Environment	Ambient temp.	Operating 0 to 55
		Storage -20 to 70
	Operating/Storage Humidity	Maximum 90% RH(non-condensing)
	Vibration Resistance	0.5G(tested with frequency range 10 to 55 Hz, X, Y, Z each direction 2H)
Structure		Open Frame
Mass (Weight) / Dimensions		Approx. 0.8kg(28.22oz) / W120×H55×D80(W1.77×H5.91×D4.72inch)
Functions	Rotation Speed	0 to 4500min ⁻¹
	Resolution (P/R)	200, 800, 1600, 3200, 6400, 12800
	Regeneration Process	Not available (External regenerative unit is optional)
	Protective Functions	Over-voltage, Regenerated voltage overload, Over-speed, Encoder disconnection, Reset error, CPU error, Overload stop, Soft Servo Error, Amplifier Overheat
	Display	Power status, Alarm (flashing indicator)
	Functions	Operation Functions : Normal Drive(incremental move , absolute move), Zero-return, push operation Point Function : 256Point Program Function : 256PRG×16Line 8PRG×512LINE
Input/ Output Signals	Switch	DIP SW1,2 : Transmission Speed Setting DIP SW3 to 6 : Axis valid / invalid(On: Activate) DIP SW7 to 10 : Terminating Resistor Setting(On: with terminating resistance) Rotary SW : Node Address Setting (0 to E)
	Input Signals	CN1 Fixed function (4) : EXE, Point, SELECT, STOP, ALMCLR CN1 Selectable (4) : Generic Input, Point, Pause, Interlock CN4 to CN7 Allocation Function(2 X 4-axis) Hard.Limit(SDN) Signal
	Output Signals	CN1 Fixed function In-Position, Ack, Busy, ALM CN1Selectable (8) Generic Output, Motor Stop, H.Limit Monitor, ZONE, Zero-return completion, END, STOP Monitor, SDN Monitor
	Communication Specifications	RS-485 Standard Start-Stop Synchronization, Half Duplex(Part numbers ending with "0" or "1") RS-485 Standard Start-Stop Synchronization, Full Duplex(Part numbers ending with "2" or "3")

Amplifier Dimensional Drawing[Unit : mm (inch)]

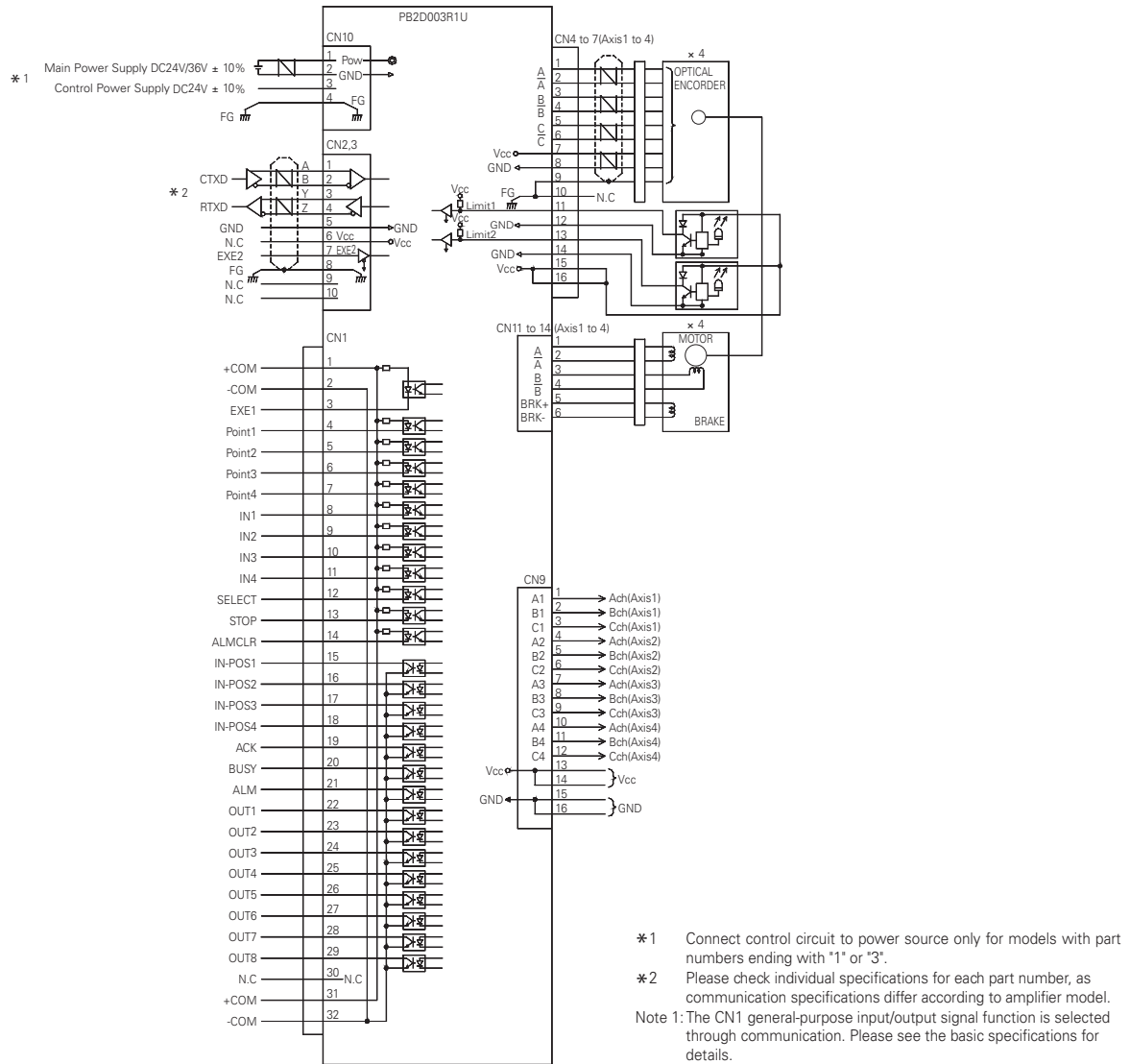


Amplifier Model Number Nomenclature

PB2D003R1U

	Communication Specifications	Power Input
0	Start-Stop Synchronization,	Single Pwr.
1	Half Duplex	Separate
2	Start-Stop Synchronization,	Single Pwr.
3	Full Duplex	Separate

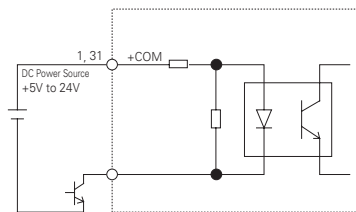
External Wiring Diagram



Input/ Output Signals Circuit

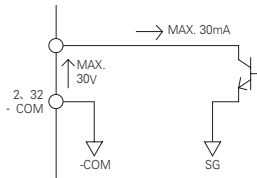
Generic Input

Input Voltage Specifications : DC5V to 24V $\pm 10\%$



Generic Output

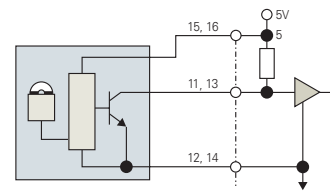
Generic Output 30 m A MAX.



Hard Limit (SDN)

Not insulated

*CN4 to 7



Features and Functions

Type R

Type P

Type M

Type R Multi-Axis

General Specifications

Motor Dimensional Drawings

Options



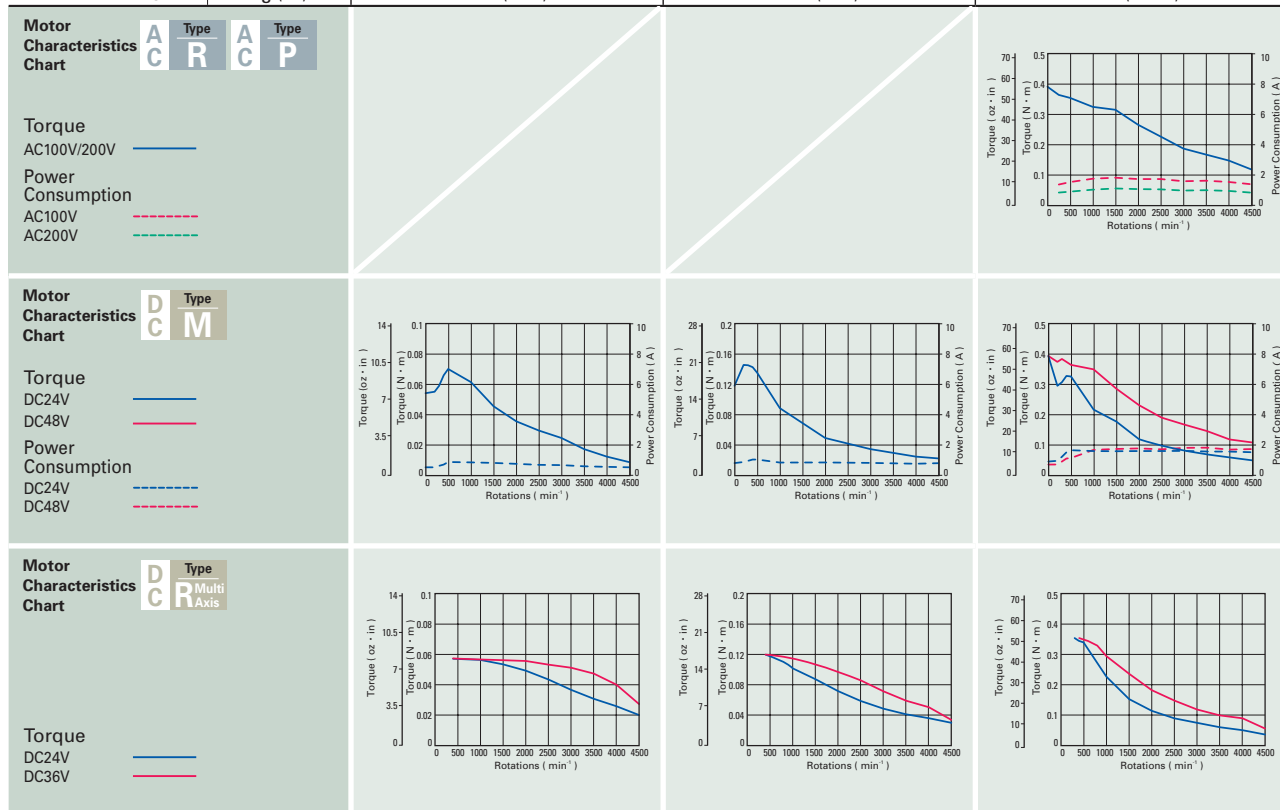
General Specifications

Standard Model

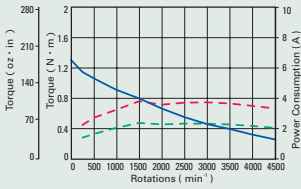
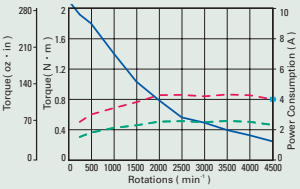
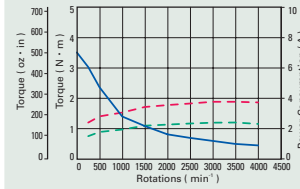
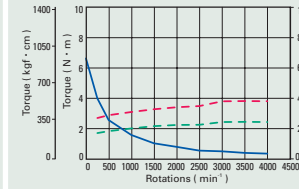
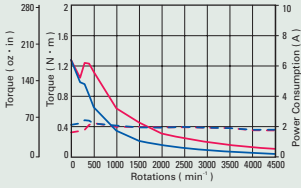
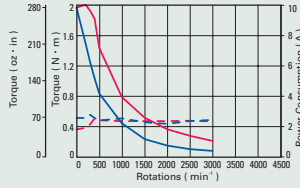
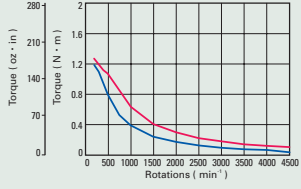
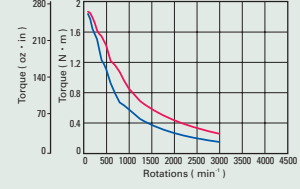
Motor Flange Size

AC	42 (1.65in)	60 (2.36in)	86 (3.39in)
DC	28 (1.1in)	42 (1.65in)	60 (2.36in)

Size	Motor Flange Size	28mm (1.10in)		42mm (1.65in)
	Motor Length	58.5mm (2.30in)	77.8mm (3.06in)	57.6mm (2.27in)
Motor Model (A C)	Unit			PBM423FXE20
Type R Set Model No.				PBAR423
Related Amplifier Model No				PB3A003R200
Type P Set Model No.				PBAP423
Related Amplifier Model No				PB3A003P200
Motor Model (D C)		PBM282FXE20	PBM284FXE20	PBM423FXE20
Type M Set Model No.		PBDM282	PBDM284	PBDM423
Related Amplifier Model No			PB3D003M200	
Motor Model (D C)		PBM282DXA20	PBM284DXA20	PBM423DXA20
Type R Multi-axis Model No.			PB2D003R1U	
MAX. Stall Torque	N · m (oz · in)	0.055(7.79)	0.115(16.28)	0.39(55.23)
Rotor Inertia	$\times 10^{-4} \text{kg} \cdot \text{m}^2$ (oz · in ²)	0.008(0.044)	0.016(0.087)	0.056(0.306)
Allowable Thrust Load	N	9.8	9.8	9.8
Allowable Radial Load ^{Note 1)}	N	33	33	49
Motor Mass (Weight)	kg (oz)	0.16(5.64)	0.23(8.11)	0.35(12.35)



* Maintain motor case temperature at a point below 85 °C.
 Note 1) The load point is determined at a position 14mm from the mounting surface.

60mm (2.36in)		86mm (3.39in)	
70.3mm (2.77in)	102.3mm (4.03in)	85.5mm (3.37in)	116mm (4.57in)
PBM603FXE20	PBM604FXE20	PBM861FXE20	PBM862FXE20
PBAR603	PBAR604	PBAR861	PBAR862
PB3A003R200			
PBAP603	PBAP604	PBAP861	PBAP862
PB3A003P200			
PBM603FXE20	PBM604FXE20		
PBDM603	PBDM604		
PB3D003M200			
PBM603DXA20	PBM604DXA20		
PB2D003R1U			
1.3(184.09)	1.9(269.05)	3.3(467.30)	6.4(906.28)
0.4(2.187)	0.84(4.593)	1.48(8.092)	3(16.402)
14.7		60	60
167		200	200
0.85(29.98)	1.42(50.09)	1.9(67.02)	3.1(109.35)
			
			
			

Features and Functions

Type R

Type P

Type M

Type R Multi-Axis

General Specifications

Motor Dimensional Drawings

Options



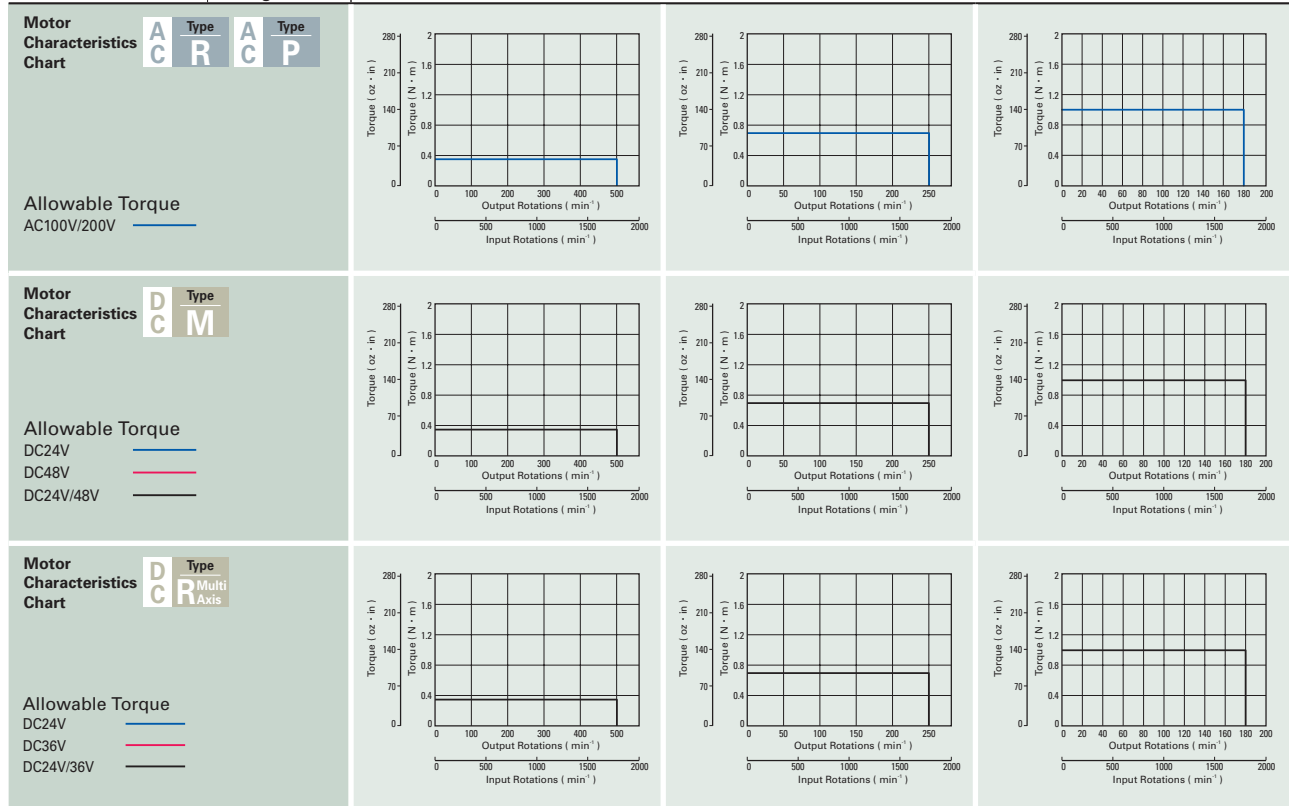
General Specifications

Low-backlash Gear Model

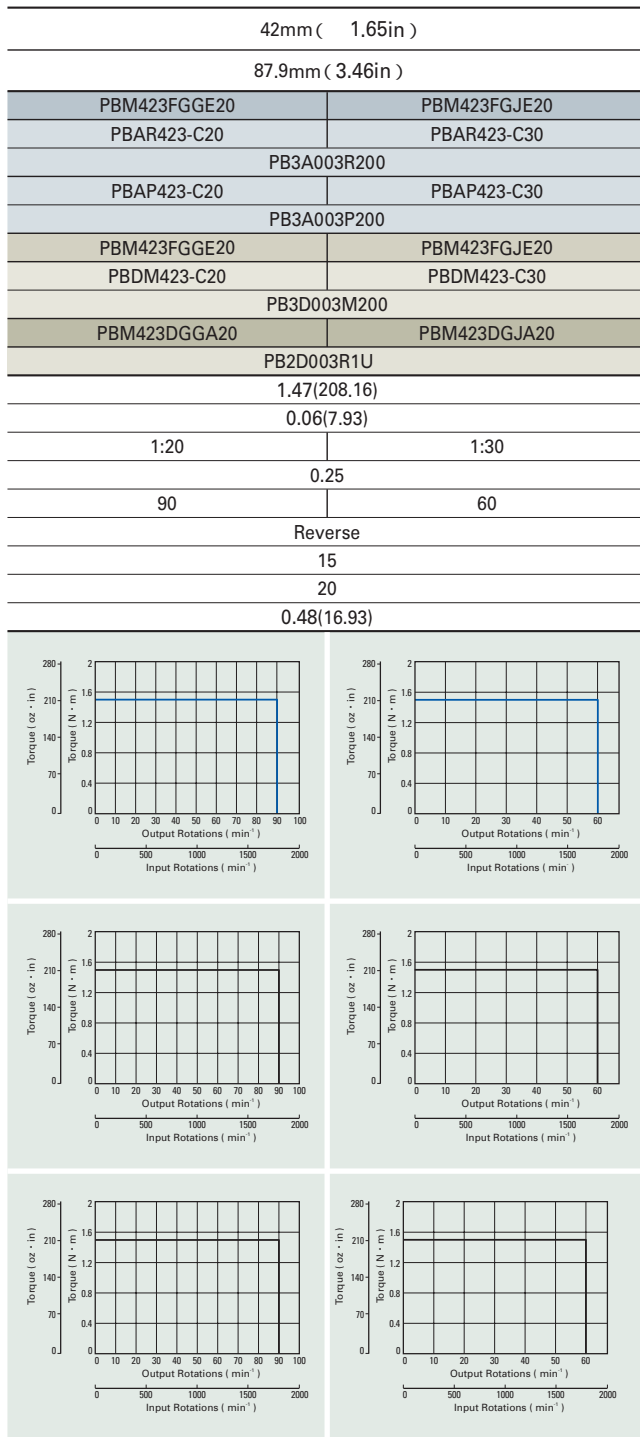
Motor Flange Size

AC	42 (1.65in)	60 (2.36in)
DC	42 (1.65in)	60 (2.36in)

Size	Motor Flange Size	42mm (1.65in)		
	Motor Length +Gear Length	87.9mm (3.46in)		
Motor Model (A C)	Unit	PBM423FGAE20	PBM423FGBE20	PBM423FGEE20
Type R Set Model No.		PBAR423-C3.6	PBAR423-C7.2	PBAR423-C10
Related Amplifier Model No		PB3A003R200		
Type P Set Model No.		PBAP423-C3.6	PBAP423-C7.2	PBAP423-C10
Related Amplifier Model No		PB3A003P200		
Motor Model (D C)		PBM423FGAE20	PBM423FGBE20	PBM423FGEE20
Type M Set Model No.		PBDM423-C3.6	PBDM423-C7.2	PBDM423-C10
Related Amplifier Model No		PB3D003M200		
Motor Model (D C)		PBM423DGAA20	PBM423DGBA20	PBM423DGEA20
Type R Multi-axis Model No.		PB2D003R1U		
MAX. Stall Torque	N · m (oz · in)	0.343(48.57)	0.686(97.14)	0.98(138.77)
Rotor Inertia	$\times 10^{-4} \text{kg} \cdot \text{m}^2$ (oz · in ²)	0.06(7.93)		
Reduction Gear Ratio		1:3.6	1:7.2	1:10
Backlash	DEG	0.6	0.4	0.35
Allowable Rotations	min ⁻¹	500	250	180
Rotation Direction	Rel. to command dir.	Forward		
Allowable Thrust Load	N	15		
Allowable Radial Load ^{Note 1)}	N	20		
Motor Mass (Weight)	kg (oz)	0.48(16.93)		



*Maintain motor case temperature at a point below 85 °C.
Note 1) The load point is determined at a position 1/3 of the length from the output shaft.



Features and Functions

Type R

Type P

Type M

Type R Multi-Axis

General Specifications

Motor Dimensional Drawings

Options



General Specifications

Low-backlash Gear Model

Motor Flange Size

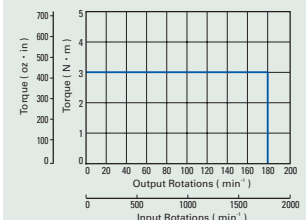
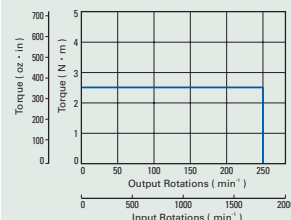
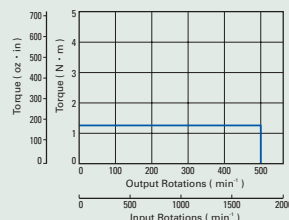
AC	42 (1.65in)	60 (2.36in)
DC	42 (1.65in)	60 (2.36in)

Size	Motor Flange Size	60mm (2.36in)		
	Motor Length +Gear Length	115.8mm (4.56in)		
Motor Model (A C)	Unit	PBM603FGAE20	PBM603FGBE20	PBM603FGEE20
Type R Set Model No.		PBAR603-C3.6	PBAR603-C7.2	PBAR603-C10
Related Amplifier Model No		PB3A003R200		
Type P Set Model No.		PBAP603-C3.6	PBAP603-C7.2	PBAP603-C10
Related Amplifier Model No		PB3A003P200		
Motor Model (D C)		PBM603FGAE20	PBM603FGBE20	PBM603FGEE20
Type M Set Model No.		PBDM603-C3.6	PBDM603-C7.2	PBDM603-C10
Related Amplifier Model No		PB3D003M200		
Motor Model (D C)		PBM603DGAA20	PBM603DGBA20	PBM603DGEA20
Type R Multi-axis Model No.		PB2D003R1U		
MAX. Stall Torque	N · m (oz · in)	1.25(177.01)	2.5(354.02)	3(424.82)
Rotor Inertia	$\times 10^{-4} \text{kg} \cdot \text{m}^2$ (oz · in ²)	0.4(2.19)		
Reduction Gear Ratio		1:3.6	1:7.2	1:10
Backlash	DEG	0.55	0.25	
Allowable Rotations	min ⁻¹	500	250	180
Rotation Direction	Rel. to command dir.	Forward		Reverse
Allowable Thrust Load	N	30		
Allowable Radial Load ^{Note 1)}	N	100		
Motor Mass (Weight)	kg (oz)	1.22(43.03)		

Motor Characteristics Chart

AC Type R AC Type P

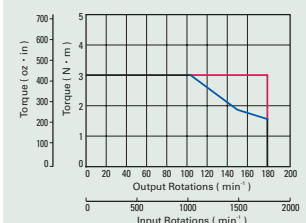
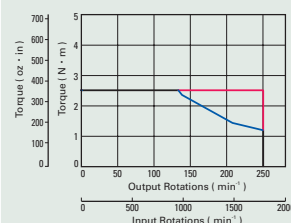
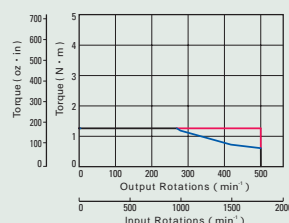
Allowable Torque
AC100V/200V



Motor Characteristics Chart

DC Type M

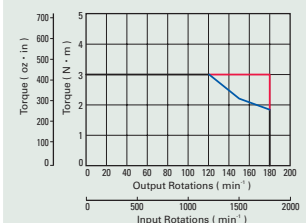
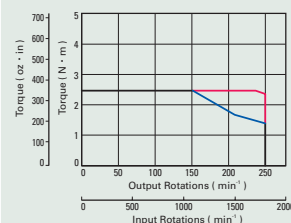
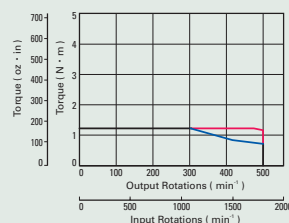
Allowable Torque
DC24V
DC48V
DC24V/48V



Motor Characteristics Chart

DC Type R Multi-Axis

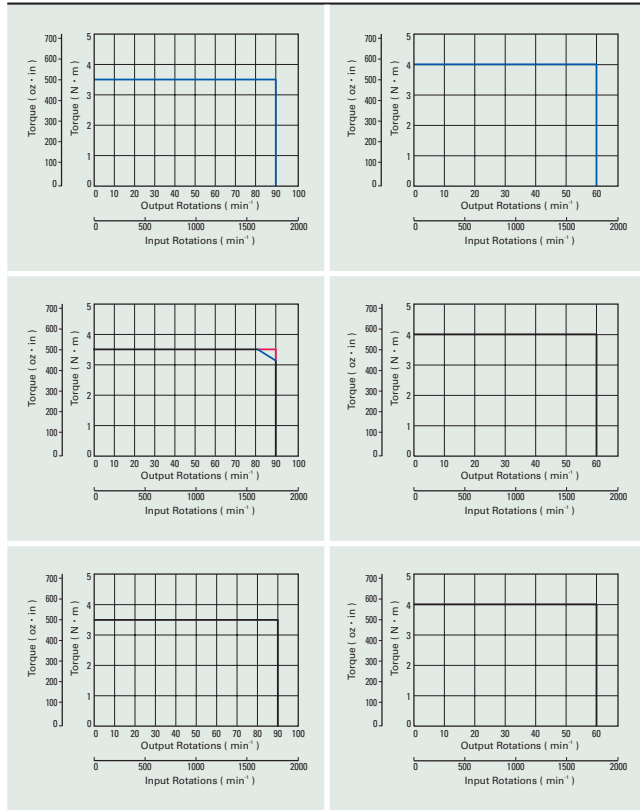
Allowable Torque
DC24V
DC36V
DC24V/36V



* Maintain motor case temperature at a point below 85 °C.

Note 1) The load point is determined at a position 1/3 of the length from the output shaft.

60mm (2.36in)	
115.8mm (4.56in)	
PBM603FGGE20	PBM603FGJE20
PBAR603-C20	PBAR603-C30
PB3A003R200	
PBAP603-C20	PBAP603-C30
PB3A003P200	
PBM603FGGE20	PBM603FGJE20
PBDM603-C20	PBDM603-C30
PB3D003M200	
PBM603DGGGA20	PBM603DGJA20
PB2D003R1U	
3.5(495.62)	4(566.43)
0.4(2.19)	
1:20	1:30
0.17	
90	60
Reverse	
30	
100	
1.22(43.03)	



Features and Functions

Type R

Type P

Type M

Type R Multi-Axis

General Specifications

Motor Dimensional Drawings

Options



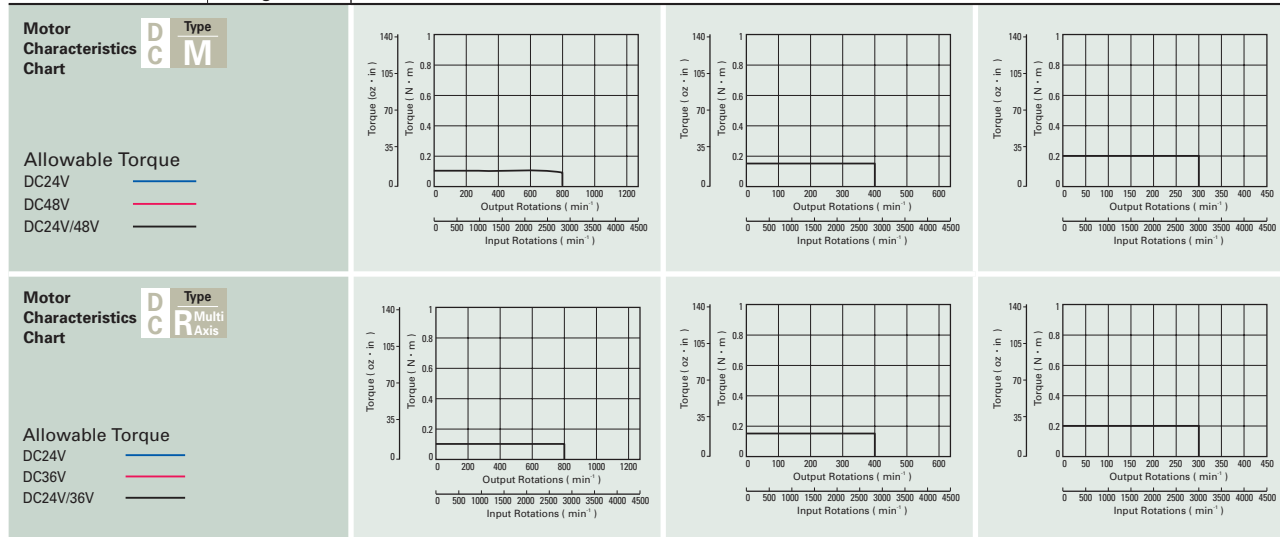
General Specifications

Spur Gear Model

Motor Flange Size

DC 28

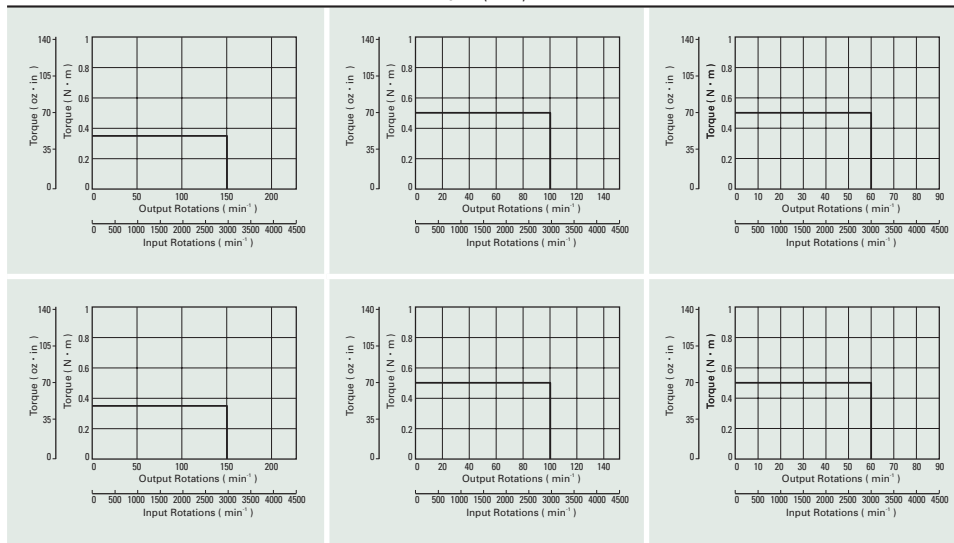
Size	Motor Flange Size	28mm (1.10in)		
	Motor Length + Gear Length	88.5mm (3.48in)		
Motor Model (D C)	Unit	PBM282FGAE20	PBM282FGBE20	PBM282FGEE20
Type M Set Model No.		PBDM282-G3.6	PBDM282-G7.2	PBDM282-G10
Related Amplifier Model No		PB3D003M200		
Motor Model (D C)		PBM282DGAA20	PBM282DGBA20	PBM282DGEA20
Type R Multi-axis Model No.		PB2D003R1U		
MAX. Stall Torque	N · m (oz · in)	0.1(14.16)	0.15(21.24)	0.2(28.32)
Rotor Inertia	$\times 10^{-4} \text{kg} \cdot \text{m}^2$ (oz · in ²)	0.02(0.09)		
Reduction Gear Ratio		1:3.6	1:7.2	1:10
Backlash	DEG	2		
Allowable Rotations	min ⁻¹	800	400	300
Rotation Direction	Rel. to command dir.	Forward		Reverse
Allowable Thrust Load	N	10		
Allowable Radial Load ^{Note 1)}	N	15		
Motor Mass (Weight)	kg (oz)	0.22(7.76)		



* Maintain motor case temperature at a point below 85 °C.

Note 1) The load point is determined at a position 1/3 of the length from the output shaft.

28mm (1.10in)		
88.5mm (3.48in)		
PBM282FGGE20	PBM282FGJE20	PBM282FGLE20
PBDM282-G20	PBDD282-G30	PBDD282-G50
PB3D003M200		
PBM282DGGA20	PBM282DGJA20	PBM282DGLA20
PB2D003R1U		
0.35(49.56)	0.5(70.80)	
0.02(0.09)		
1:20	1:30	1:50
1.5		
150	100	60
Forward		
10		
15		
0.22(7.76)		



Features and Functions

Type R

Type P

Type M

Type R Multi-Axis

General Specifications

Motor Dimensional Drawings

Options



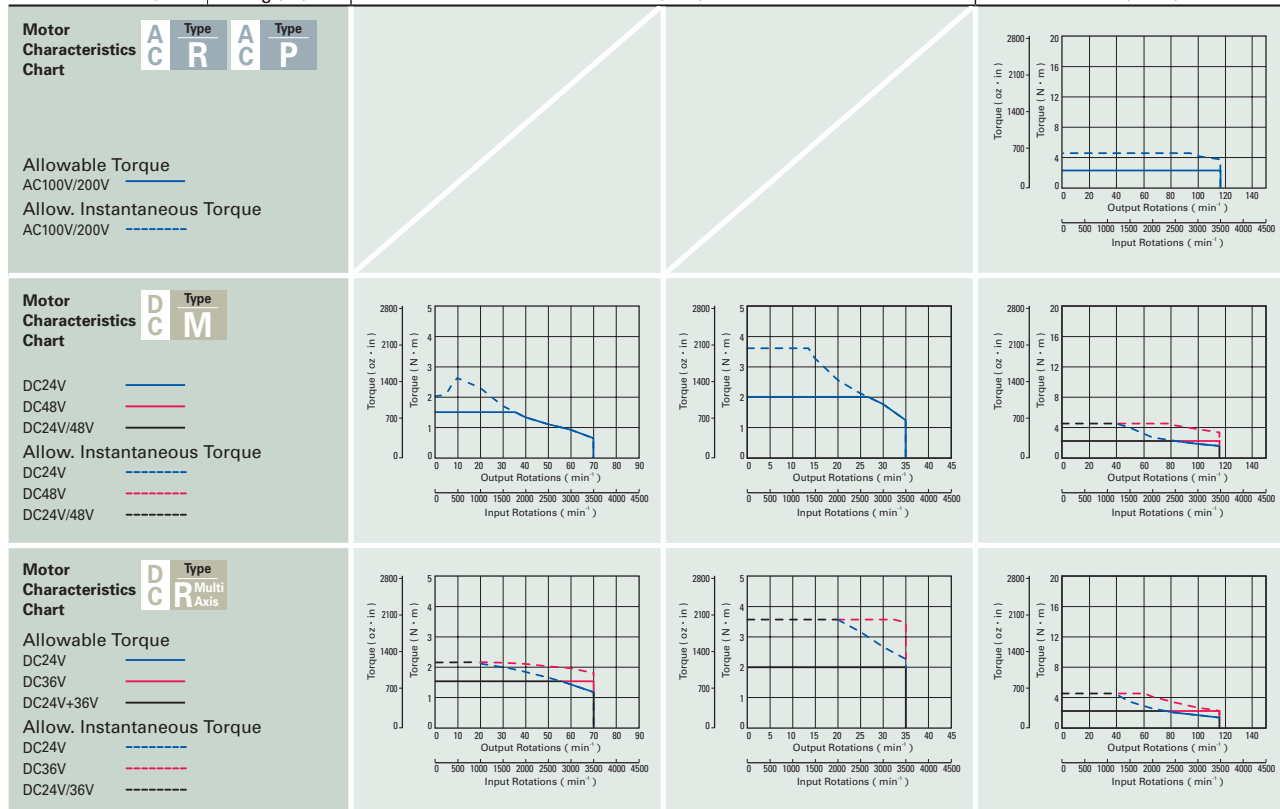
General Specifications

Harmonic Gear Model

Motor Flange Size

AC	42 (1.65in)	60 (2.36in)	
DC	28 (1.10in)	42 (1.65in)	60 (2.36in)

Size	Motor Flange Size	28mm (1.10in)		42mm (1.65in)
	Motor Length + Gear Length	97mm (3.82in)		
Motor Model (A C)	Unit			PBM423FHJE20
Type R Set Model No.				PBAR423-H30
Related Amplifier Model No				PB3A003R200
Type P Set Model No.				PBAP423-H30
Related Amplifier Model No				PB3A003P200
Motor Model (D C)		PBM282FHLE20	PBM282FHME20	PBM423FHJE20
Type M Set Model No.		PBDM282-H50	PBDM282-H100	PBDM423-H30
Related Amplifier Model No			PB3D003M200	
Motor Model (D C)		PBM282DHLE20	PBM282DHMA20	PBM423DHJA20
Type R Multi-axis Model No.			PB2D003R1U	
Allowable Torque	N · m (oz · in)	1.5(212.41)	2(283.21)	2.2(311.54)
Allow. Instantaneous Torque	N · m (oz · in)	2.7(382.34)	3.6(509.79)	4.5(637.23)
Rotor Inertia	$\times 10^{-4} \text{kg} \cdot \text{m}^2$ (oz · in ²)	0.01(0.066)		0.372
Reduction Gear Ratio		1:50	1:100	1:30
Lost Motion	min	0.4 to 3 (± 8.50oz · in)	0.4 to 3 (± 11.33oz · in)	
Hysteresis Loss	min			3.6
Allowable Rotations	min ⁻¹	70	35	116
Allowable Thrust Load	N	100		1150
Allowable Radial Load ^{Note 1)}	N	160		209
Motor Mass (Weight)	kg (oz)	0.27(9.52)		0.54(19.05)



* Maintain motor case temperature at a point below 85 °C. ** The gear output shaft rotates in the opposite direction.
Note 1) The load point is determined at a position 1/3 of the length from the output shaft.

42mm (1.65in)		60mm (2.36in)	
97mm (3.82in)		137.3mm (5.41in)	
PBM423FHLE20	PBM424FHME20	PBM603FHLE20	PBM603FHME20
PBAR423-H50	PBAR423-H100	PBAR603-H50	PBAR603-H100
PB3A003R200			
PBAP423-H50	PBAP423-H100	PBAP603-H50	PBAP603-H100
PB3A003P200			
PBM423FHLE20	PBM423FHME20	PBM603FHLE20	PBM603FHME20
PBDM423-H50	PBDM423-H100	PBDM603-H50	PBDM603-H100
PB3D003M200			
PBM423DHLE20	PBM423DHME20	PBM603DHLE20	PBM603DHME20
PB2D003R1U			
3.5(495.62)	5(708.03)	5.5(778.84)	8(1132.86)
8.3(1175.34)	11(1557.68)	14(1982.50)	20(2832.14)
0.07(0.372)		0.44(2.38)	
1:50	1:100	1:50	1:100
2.4	2.4	0.4 to 3 (± 39.65oz · in)	0.4 to 3 (± 56.64oz · in)
70	35	70	35
1150		400	
209		360	
0.54(19.05)		1.45(51.15)	

Features and Functions

Type R

Type P

Type M

Type R Multi-Axis

General Specifications

Motor Dimensional Drawings

Options



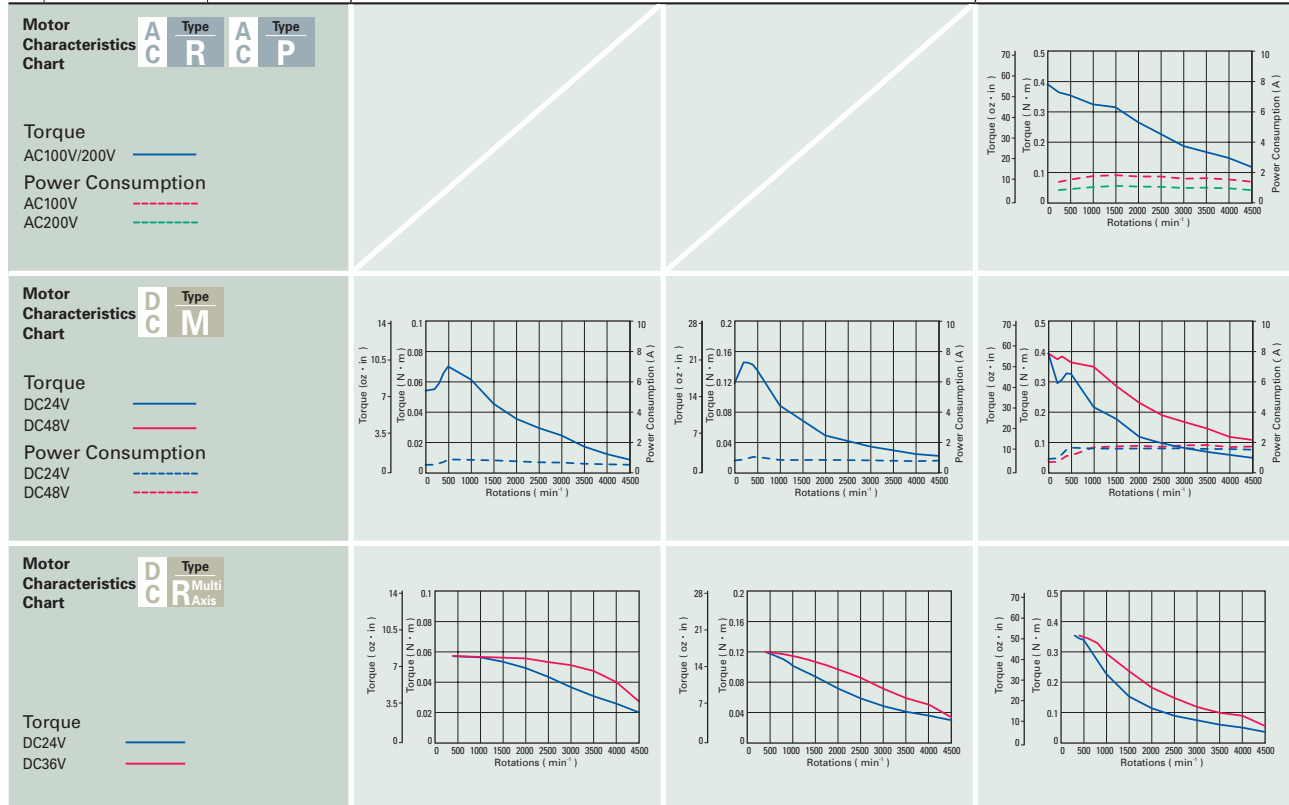
General Specifications

Electromagnetic Brake Model

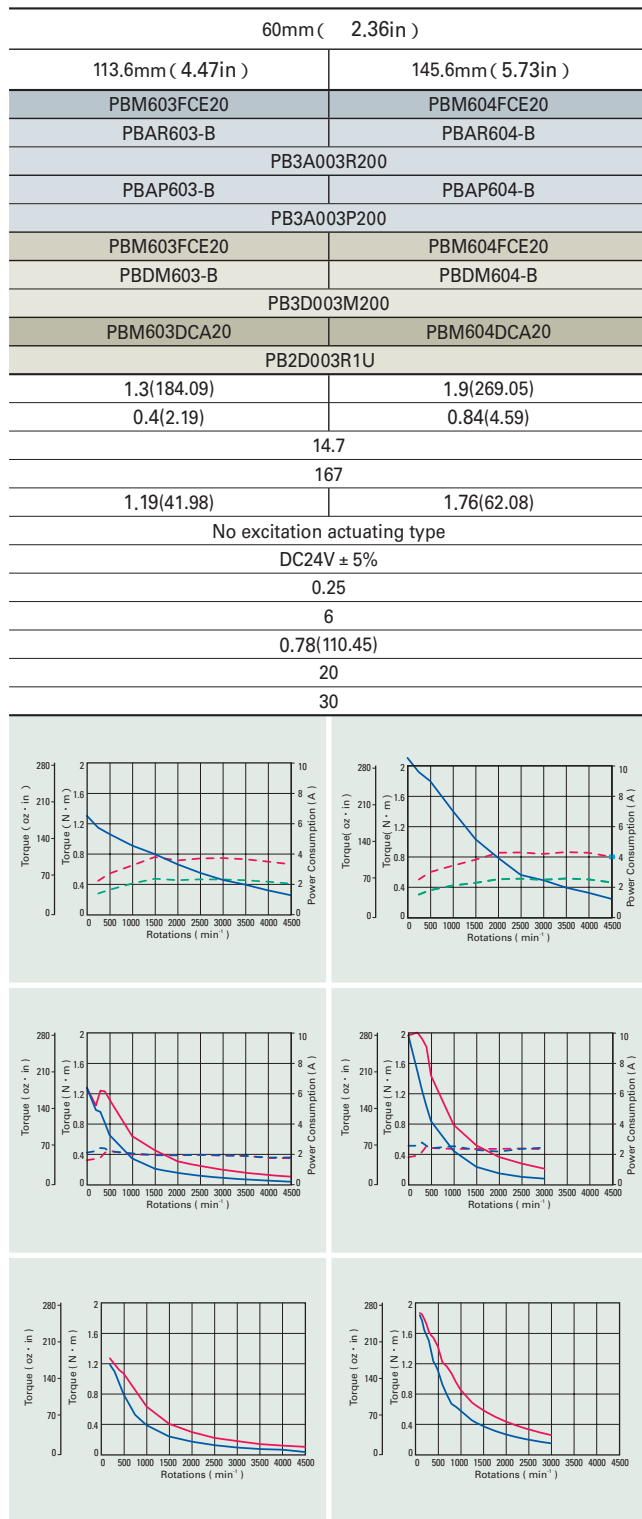
Motor Flange Size

AC	42 (1.65in)	60 (2.36in)	
DC	28 (1.10in)	42 (1.65in)	60 (2.36in)

Size	Motor Flange Size	28mm (1.10in)		42mm (1.65in)
	Motor Length + Brake Length	97.8mm (3.85in)	117.1mm (4.61in)	90mm (3.54in)
Motor Model (A C)	Unit			PBM423FCE20
Type R Set Model No.				PBAR423-B
Related Amplifier Model No				PB3A003R200
Type P Set Model No.				PBAP423-B
Related Amplifier Model No				PB3A003P200
Motor Model (D C)		PBM282FCE20	PBM284FCE20	PBM423FCE20
Type M Set Model No.		PBDM282-B	PBDM284-B	PBDM423-B
Related Amplifier Model No			PB3D003M200	
Motor Model (D C)		PBM282DCA20	PBM284DCA20	PBM423DCA20
Type R Multi-axis Model No.			PB2D003R1U	
MAX. Stall Torque	N · m (oz · in)	0.06(7.79)	0.12(16.28)	0.39(55.23)
Rotor Inertia	$\times 10^{-4} \text{kg} \cdot \text{m}^2$ (oz · in ²)	0.01(0.04)	0.02(0.09)	0.06(0.31)
Allowable Thrust Load	N	9.8	9.8	9.8
Allowable Radial Load ^{Note 1)}	N	33	33	49
Motor Mass (Weight)	kg (oz)	0.28(9.88)	0.35(12.35)	0.5(17.64)
Electromagnetic Brake	Operation Method	No excitation actuating type		
	Power Voltage	DC24V \pm 5%		
	Excitation Current	0.15		
	Power Consumption	3.6		
	Friction Torque	0.05(6.94)		
	Brake Engage Time	20		
	Brake Release Time	20		



*Maintain motor case temperature at a point below 85 °C. Note 1) The load point is determined at a position 1/3 of the length from the output shaft.



Features and Functions

Type R

Type P

Type M

Type R Multi-Axis

General Specifications

Motor Dimensional Drawings

Options

Unit : inch

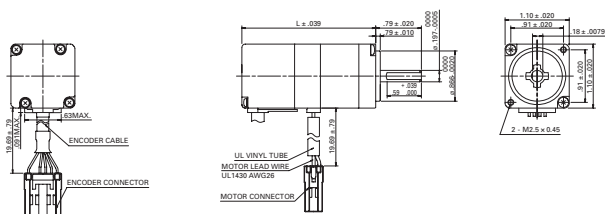
28mm (1.10inch), 42mm (1.65inch), 60mm (2.36inch)

28mm (1.10inch)

Standard Model

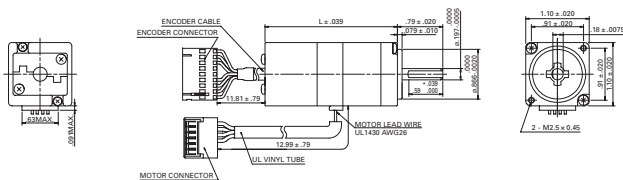
PBM282FXE20 DC

PBM284FXE20 DC



PBM282DXA20 DC Multi Axis

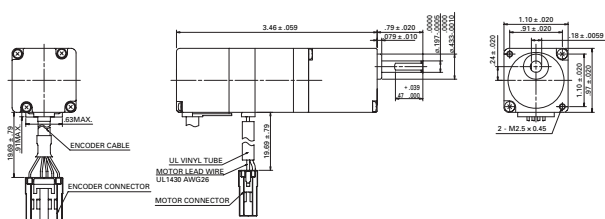
PBM284DXA20 DC Multi Axis



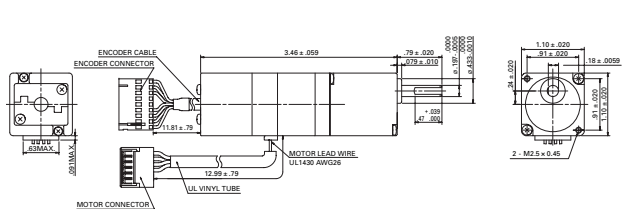
MODEL	L
PBM282	2.30
PRM284	3.06

Spur Gear Model

PBM282FG E20 DC

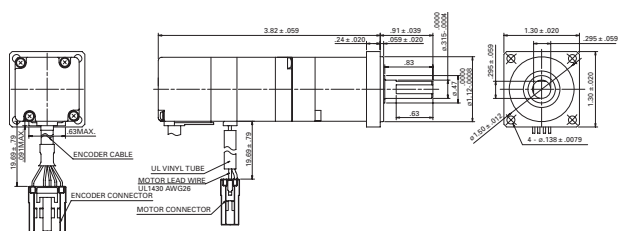


PBM282DG A20 DC Multi Axis

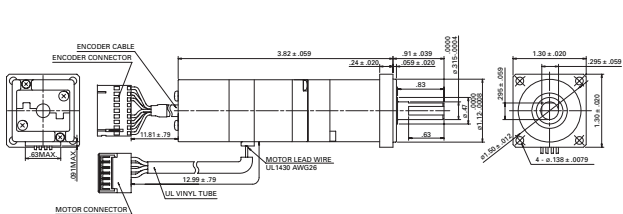


Harmonic Gear Model

PBM282FH E20 DC



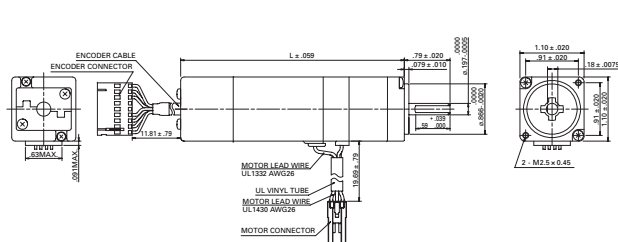
PBM282DH A20 DC Multi Axis



Electromagnetic Brake Model

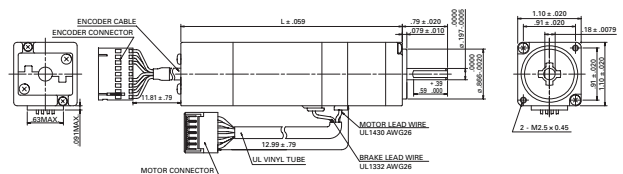
PBM282FCE20 DC

PBM284FCE20 DC



PBM282DCA20 DC Multi Axis

PBM284DCA20	DC	Multi Axis
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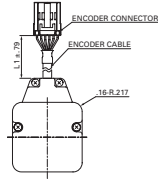


MODEL	L
PBM282	3.85
PBM284	4.61

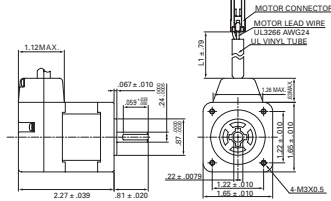
42mm (1.65inch)

Standard Model

PBM423FXE20 **AC** **DC**



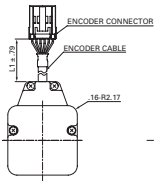
PBM423DXA20 **DC** Multi Axis



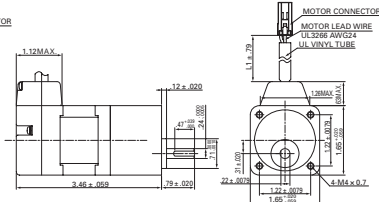
MODEL	L1
PBM423FXE20	19.69
PBM423DXA20	11.81

Low Backlash Gear Model

PBM423FG E20 **AC** **DC**



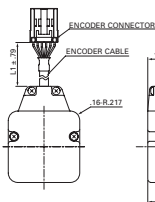
PBM423DG A20 **DC** Multi Axis



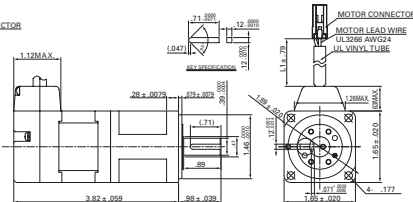
MODEL	L1
PBM423FG E20	19.69
PBM423DG A20	11.81

Harmonic Gear Model

PBM423FH E20 **AC** **DC**



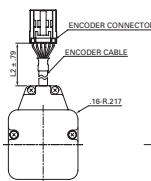
PBM423DH A20 **DC** Multi Axis



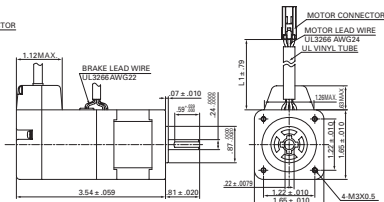
MODEL	L1
PBM423FH E20	19.69
PBM423DH A20	11.81

Electromagnetic Brake Model

PBM423FCE20 **AC** **DC**



PBM423DCA20 **DC** Multi Axis

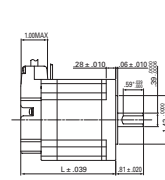
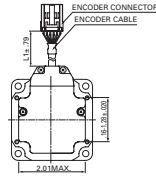


MODEL	L1	L2
PBM423FCE20	20.28	19.69
PBM423DCA20	12.40	11.81

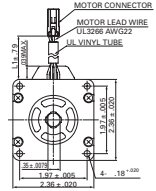
60mm (2.36inch)

Standard Model

PBM603FXE20 **AC** **DC**
PBM604FXE20 **AC** **DC**



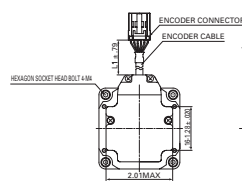
PBM603DXA20 **DC** Multi Axis
PBM604DXA20 **DC** Multi Axis



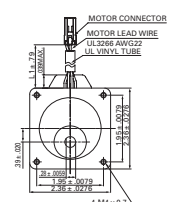
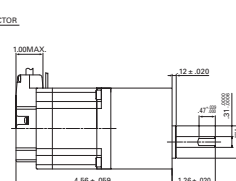
MODEL	L	L1
PBM603FXE20	2.77	19.69
PBM604FXE20	4.03	19.69
PBM603DXA20	2.77	11.81
PBM604DXA20	4.03	11.81

Low Backlash Gear Model

PBM603FG E20 **AC** **DC**



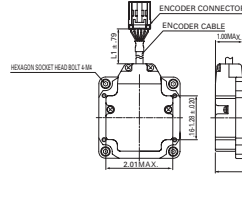
PBM603DG A20 **DC** Multi Axis



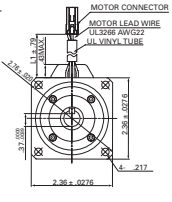
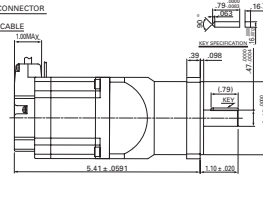
MODEL	L1
PBM603FG E20	19.69
PBM603DG A20	11.81

Harmonic Gear Model

PBM603FH E20 **AC** **DC**



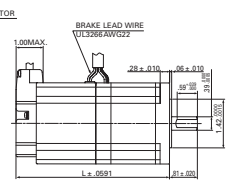
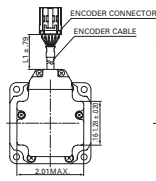
PBM603DH A20 **DC** Multi Axis



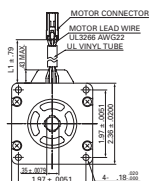
MODEL	L1
PBM603FH E20	19.69
PBM603DH A20	11.81

Electromagnetic Brake Model

PBM603FCE20 **AC** **DC**
PBM604FCE20 **AC** **DC**



PBM603DCA20 **DC** Multi Axis
PBM604DCA20 **DC** Multi Axis



MODEL	L	L1
PBM603FCE20	4.47	19.69
PBM604FCE20	5.73	19.69
PBM603DCA20	4.47	11.81
PBM604DCA20	5.73	11.81

Features and Functions

Type R

Type P

Type M

Type R Multi-Axis

General Specifications

Motor Dimensional Drawings

Options

Motor Dimensional Drawings

Unit : inch

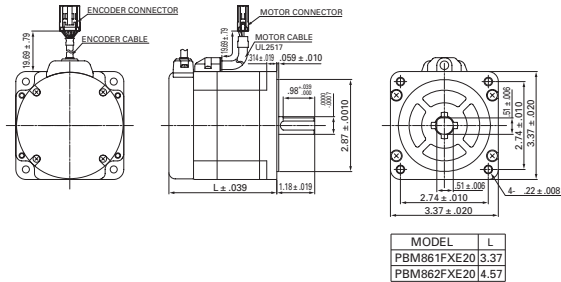
86mm (3.39 inch)

86mm (3.39inch)

Standard Model

PBM861FXE20 **AC**

PBM862FXE20 **AC**



Connector Specification Of Motor Side

AC **DC**

Encoder Connector

Housing : 1-1318118-6
Terminal : 1318106-1
Manufacturer : AMP

Motor Connector

Housing : 1-1318119-3
Terminal : 1318105-1
Manufacturer : AMP

DC Multi-axis

Encoder Connector

Housing : 51030-0930
Terminal : 50083-8070
Manufacturer : MOLEX

Motor Connector

Housing : 5111-0610
Terminal : 50397-8000
Manufacturer : MOLEX

Connector Connection Of Encoder Side

PIN No.	LEAD COLR	
A1	Blue	CHANNEL A
B1	Brown	CHANNEL Ā
A2	Green	CHANNEL B
B2	Purple	CHANNEL B̄
A3	White	CHANNEL C
B3	Yellow	CHANNEL C̄
A4	Red	+5V
B4	Black	0V
A5	N.C.	
B5	Orange	OVER HEAT
A6	Black	Shield
B6	N.C.	

Encoder Cable : UL20276

Connector Connection Of Motor Side

Standard Model, Low Backlash Gear Model, Harmonic Gear Model

PIN No.	LEAD COLR	
A1	Blue	Motor Lead Wire
B1	Orange	Motor Lead Wire
A2	Red	Motor Lead Wire
B2	Yellow	Motor Lead Wire
A3	N.C.	
B3	N.C.	

Electromagnetic Brake Model

PIN No.	LEAD COLR	
A1	Blue	Motor Lead Wire
B1	Orange	Motor Lead Wire
A2	Red	Motor Lead Wire
B2	Yellow	Motor Lead Wire
A3	Brake +	Brake Lead Wire
B3	Brake -	Brake Lead Wire

Connector Connection Of Encoder Side

2 Channel

PIN No.	LEAD COLR	
1	Blue	CHANNEL A
2	Brown	CHANNEL Ā
3	Green	CHANNEL B
4	Purple	CHANNEL B̄
5	N.C.	
6	N.C.	
7	Red	+5V
8	Black	0V
9	Black	FG (Shield)

Encoder Cable : UL20121

(3 Channel)

PIN No.	LEAD COLR	
1	Blue	CHANNEL A
2	Brown	CHANNEL Ā
3	Green	CHANNEL B
4	Purple	CHANNEL B̄
5	White	CHANNEL C
6	Yellow	CHANNEL C̄
7	Red	+5V
8	Black	0V
9	Black	FG (Shield)

Encoder Cable : UL20276

Connector Connection Of Motor Side

Standard Model, Low Backlash Gear Model, Harmonic Gear Model

PIN No.	LEAD COLR	
1	Blue	Motor Lead Wire
2	Orange	Motor Lead Wire
3	Red	Motor Lead Wire
4	Yellow	Motor Lead Wire
5	N.C.	
6	N.C.	

Electromagnetic Brake Model

PIN No.	LEAD COLR	
1	Blue	Motor Lead Wire
2	Orange	Motor Lead Wire
3	Red	Motor Lead Wire
4	Yellow	Motor Lead Wire
5	Brake +	Brake Lead Wire
6	Brake -	Brake Lead Wire

Options

□PC Interface Description

PC Interface Software Display Screens



1:Program Input Screen



2:Point Input Screen



3:Parameter Input Screen

PB-R PC Interface Software Functions

Functions

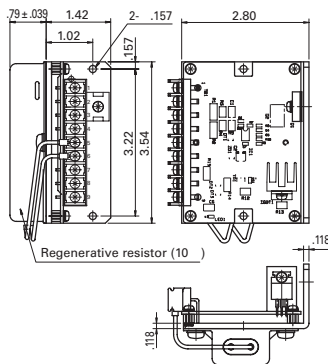
Direct command capability
Point data editing/execution
Program data editing/execution
Current position/Alarm/Amplifier status monitoring
Lead Pitch Conversion
Off-line Editing
Teaching Function, etc

Program Functions

Various branching conditions (Position, Input Port, Direct, Motor Stop)
Timer Wait
Subroutine Structure
Loop Counter, etc.

Regenerative Unit (DC For Type R Multi-axis) (Unit:inch)

Model : PBFE-01



Note 1 : TB1-Connector block wiring screw M3
Tightening torque 0.6 N · m (84.96 oz · in)
Note 2 : The external regenerative resistor is mounted on the rear surface

Features and Functions

Type R

Type P

Type M

Type R Multi-Axis

General Specifications

Motor Dimensional Drawings

Options

Precautions For Adoption

Cautions

Failure to follow the precautions on the right may cause moderate injury and property damage, or in some circumstances, could lead to a serious accident. Always follow all listed precautions.

Cautions

- Read the accompanying Instruction Manual carefully prior to using the product.
- If applying to medical devices and other equipment affecting people's lives, please contact us beforehand and take appropriate safety measures.
- If applying to equipment that can have significant effects on society and the general public, please contact us beforehand.
- Do not use this product in an environment where vibration is present, such as in a moving vehicle or shipping vessel.
- Do not perform any retrofitting, re-engineering, or modification to this equipment.
- The amplifiers presented in this catalog are meant to be used for general industrial applications. If using for special applications related to aviation and space, nuclear power, electric power, submarine repeaters, etc., please contact us beforehand.

* For any question or inquiry regarding the above, contact our Sales Department.

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*Remarks : Specifications Are Subject To Change Without Notice.

CATALOG NO. 845-1 '07.4.N